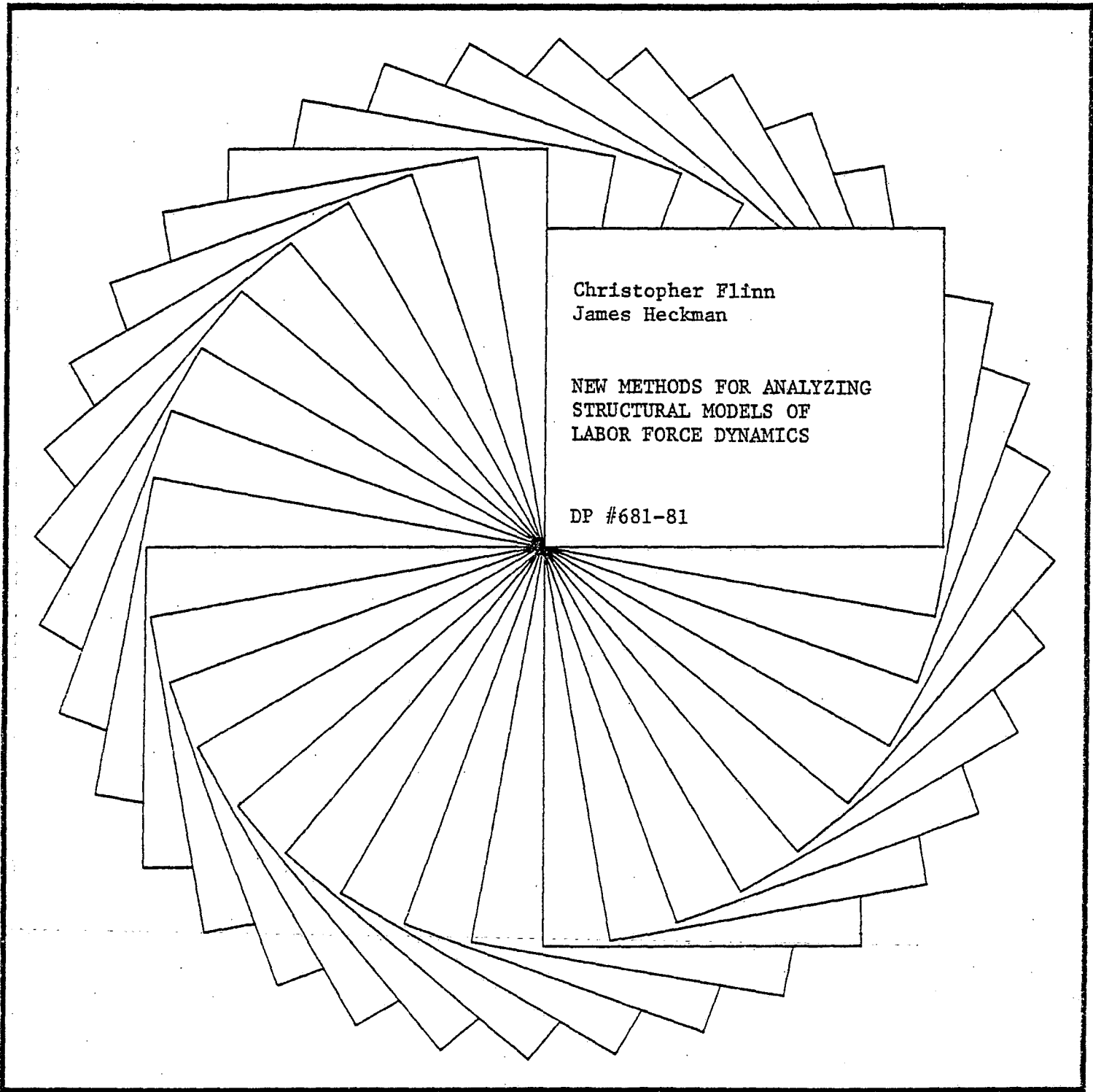# IRP Discussion Papers

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NEW METHODS FOR ANALYZING
STRUCTURAL MODELS OF
LABOR FORCE DYNAMICS

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New Methods for Analyzing Structural Models

of Labor Force Dynamics

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ABSTRACT

This paper takes a first step toward developing econometric models
for the structural analysis of labor force dynamics. Our analysis is
presented in continuous time, although most of the points raised here
can be applied to discrete time models. We show that in previous attempts
to estimate "structural" models of job search, a key source of information
necessary to identify certain structural parameters has been neglected.

We discuss the conditions under which structural search models can
be estimated. In particular, the wage offer distribution must be <u>recoverable</u>--
i.e., it must be the case that the parameters of the untruncated wage
offer distribution be estimable from the truncated accepted wage distri-
bution. The wage offer distribution must be assumed to belong to a para-
metric family. Estimates of structural parameters are shown to be sensitive
to the distributional assumption made.

A partial equilibrium two state model of employment dynamics is
estimated, using data from the National Longitudinal Survey of Young
Men. We find employment and nonemployment rates implied by the structural
parameter estimates to be generally consistent with those observed for
the population of young males.

New Methods for Analyzing Structural Models
of Labor Force Dynamics

This paper presents new econometric methods for the analysis of
labor force dynamics. The economic models we discuss assume that rational
agents make choices about their employment and labor force activity in
the face of uncertainty about key aspects of their labor market environ-
ment. A variety of such models has recently appeared in the literature
(e.g., Burdett and Mortensen, 1978 and 1980; Lucas and Prescott, 1974;
Wilson, 1980; Lippman and McCall, 1976a, b, 1981) and research in the
area continues to flourish. Theoretical results already in hand offer
possible explanations for frictional unemployment, on-the-job wage growth,
job turnover and wage dispersion.

To date there has been little systematic econometric analysis of
these models although qualitative implications obtained from these models
have sometimes been used as loose guides to interpreting unemployment
duration regressions. The few attempts at developing econometric pro-
cedures to estimate this class of models are direct transcriptions of
econometric models used to estimate reservation wages in the analysis
of female labor supply.[1] A clear analysis of identification criteria
and estimation methods for models of labor force dynamics does not appear
in the literature.

This paper takes a first step toward developing econometric models
that implement and extend the new theory. A key feature of the class of

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[1]For a survey of such models see Heckman and MaCurdy (1981). See
also the discussion in Appendix C which makes precise the statement in the
text.

economic models that we consider is that they produce predictions about the dynamics of individual behavior. With the recent wide-scale availability of longitudinal labor market data with repeated observations on individuals it has become possible to test the implications of the new microdynamic models using microdynamic data. The goal of this paper is to develop procedures to enable analysts to apply the new theories to the new data.

This paper makes three contributions. First, economic theory is used to derive the appropriate econometric specification for three models of labor force dynamics. They are (a) a continuous time single spell model of search unemployment, (b) an equilibrium continuous time two state model of employment and nonemployment, and (c) a three state model of employment, unemployment and nonmarket activity.

Second, we present new identification criteria that must be satisfied in order to estimate the structural parameters of the three models considered in this paper. We distinguish structural parameters that can be estimated using nonparametric procedures from structural parameters that can only be identified if arbitrary functional forms are assumed. One identification condition ("recoverability") applies to all econometric models for the analysis of truncated data. An important conclusion of our analysis is that most econometric models for the analysis of truncated data are nonparametrically underidentified, and some are parametrically underidentified as well.

Our third contribution recognizes that maximum likelihood estimators for most of the models considered here are nonregular. We develop an

appropriate asymptotic theory for the nonregular case that arises in the economic models analyzed in this paper, and in other econometric models derived from optimization theory.[1]

The plan of this paper is as follows. We first consider in detail a model for a single spell of an unemployed worker's search from a known distribution of wage offers. Most of the new econometric points that arise in the analysis of the economically more interesting models that follow also appear in the simpler setting of the one state model of search.

The second part of the paper is devoted to analysis of a new equilibrium two state model of employment and nonemployment. Empirical estimates of this model are presented. An appendix presents a three state model of labor force dynamics which introduces nonmarket activity into conventional search models and provides a structural economic motivation for the competing risks model widely used in social science.[2] The paper concludes with a summary.

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[1] For example, frontier production theory see, e.g., Aigner and Chu (1968), Greene (1980) and Forsund, Lovell and Schmidt (1980).

[2] For much more extensive discussion of this model see (Coleman and Heckman, 1981).

1. Estimation of a One State Model of Search Unemployment

1.0 Introduction

In this section, we consider estimation of a single spell model of an unemployed worker's search from a known distribution of wage offers using longitudinal data on a random sample of agents. Despite the fact that this model is widely cited as a justification for much empirical research on unemployment and despite previous attempts at "structural estimation" in this model, a number of important econometric aspects of this model have been neglected.

We first present a continuous time economic model for a stationary environment. We compare the continuous time model to previous discrete time formulations. We then consider issues of identification and estimation first under the assumption of no interpersonal variation in parameters ("no heterogeneity") and then with such variation ("heterogeneity"). In a concluding subsection, we consider econometric issues for a nonstationary search model.

1.1 A One State Model of Search Unemployment

This model is well exposited in Lippman and McCall (1976a). Agents are assumed to be income maximizers (here and in the rest of the paper). If an instantaneous cost c is incurred, job offers arrive from a Poisson process with parameter λ independent of the level of c (c $\geq$ 0). The probability of receiving a wage offer in time interval Δt is $\lambda \Delta t + o(\Delta t)$.[1] The probability of two or more job offers in interval Δt is thus negligible.[2]

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[1] $o(\Delta t)$ is defined as a term such that $\displaystyle \lim_{\Delta t \to o} \frac{o(\Delta t)}{\Delta t} \to 0$.

[2] For one justification of the Poisson wage arrival assumption see, e.g., Burdett and Mortensen (1978).

Successive wage offers are independent realizations from a known

absolutely continuous wage distribution F(x) with finite mean that is

assumed to be common to all agents (until Section 1.5). Once refused,

wage offers are no longer available. Jobs last forever and there is no

on the job search. Workers live forever. (But see the discussion

in Section 1.5.C.) The instantaneous rate of interest is $r(>0)$.

"V" is the value of search. Using Bellman's optimality principle for

dynamic programming (See, e.g., Ross (1970)) V may be decomposed into three

components plus a negligible component (of order $o(\Delta t)$).

(1.1) $$V = - \frac{c\Delta t}{1+r\Delta t} + \frac{(1-\lambda\Delta t)}{1+r\Delta t} V + \frac{\lambda\Delta t}{1+r\Delta t} E \max \left[\frac{x}{r} \; ; \; V \right] + o(\Delta t)$$

for $V > 0$

$= 0$ otherwise

The first term on the right of (1.1) is the discounted cost of search

in interval Δt. The second term is the probability of not receiving an

offer $(1-\lambda\Delta t)$ times the discounted value of search at the end of interval

Δt. The third term is the probability of receiving a wage offer $(\lambda\Delta t)$

times the discounted value of the expected value (computed with respect

to F(x)) of the maximum of the two options confronting the agent who

receives a wage offer: to take the offer (with present value x/r) or to

continue searching (with present value V). Note that equation

(1.1)   is defined only for $V>0$. If $V = 0$, we may define the agent as

out of the labor force (See Lippman and McCall, 1976a). From stationarity,

once out the agent is always out. Sufficient to ensure the existence of

an optimal reservation wage policy in this model is $E(|x|) < \infty$ (Robbins, 1970).

Collecting terms in (1.1) and passing to the limit, we reach the familiar formula (Lippman and McCall, 1976a)

$$(1.2) \qquad c + rV = \frac{\lambda}{r} \int_{rV}^{\infty} (x-rV)dF(x) \quad \text{for } V>0.$$

"rV" is the reservation wage. It is implicitly determined from (1.2). For any offered wage $x \geq rV$, the agent accepts the offer. The probability that an offer is unacceptable is $F(rV)$.

If $r=0$, an optimal policy still exists if $E(|\ell|) < \infty$ where ℓ is the lump sum value of the job offer over the infinite horizon. A reservation value R exists. It is determined as the solution to

$$(1.2)' \qquad c = \lambda \int_{R}^{\infty} (\ell-R)dG(\ell) \quad \text{if } R>0$$

where $G(\ell)$ is the cdf of ℓ.

To calculate the probability that an unemployment spell T_u exceeds t_u, two ingredients are required. First, we must compute the probability that j offers are received in time interval t_u. By assumption this is

$$(1.3) \qquad \text{Prob}(j \text{ offers} \mid t_u) = \frac{(\lambda t_u)^j e^{-\lambda t_u}}{j!}, \quad (\lambda > 0).$$

We next need to compute the probability that none of the j offers is acceptable. This is $[F(rV)]^j$. Assuming independence of arrival times and wage offers, the <u>survivor function</u> $P(T_u > t_u)$ is the product of these two probabilities summed over all j, <u>i.e.</u>,

$$(1.4) \qquad P(T_u > t_u) = \sum_{j=0}^{\infty} \frac{(\lambda t_u)^j}{j!} e^{-\lambda t_u} [F(rV)]^j$$

$$= e^{-\lambda(1 - F(rV))t_u} \qquad (1)$$

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[1](The power series expansion definition of the exponential is used in the final step.)

So that the density of t_u is $f(t_u) = \lambda(1-F(rV))e^{-\lambda(1-F(rV))t_u}$.

Accepted wages are truncated random variables with rV as the lower point of truncation. The density of accepted wages is

$$(1.5) \qquad f(x|x>rV) = \frac{f(x)}{1-F(rV)}, \quad x \geq rV.$$

Thus the one spell search model has the same statistical structure for accepted wages as other models of self-selection in labor economics (Lewis, 1974; Heckman, 1974 and Heckman and MaCurdy, 1981).

From the assumption that wages are distributed independently of wage arrival times, the joint density of duration times t_u and accepted wages (x) is the product of the density of each random variable.

$$m(t_u,x) = \{\lambda(1 - F(rV))\exp - \lambda(1 - F(rV))t_u\} \frac{f(x)}{1-F(rV)}$$

$$= (\lambda \exp -\lambda(1 - F(rV))t_u)f(x), \quad x \geq rV.$$

The stationary search model generates a duration model with a constant hazard rate $h_u(t_u)$ where

$$(1.6) \qquad h(t_u) = - \frac{d \ln P(T_u > t_u)}{dt_u} = \lambda(1 - F(rV)).$$

Higher values of the hazard are associated with more rapid exit from the unemployment state. A model with a constant hazard is said to exhibit no duration dependence $\left(\frac{dh(t_u)}{dt_u} = 0 \right)$.

Differentiation of (1.2) (and integration by parts) reveals that the reservation wage increases with positive translations of the wage offer distribution, decreases in the cost of search, increases in the rate of wage arrivals (λ), and decreases in the rate of interest. The hazard rate $(h(t_u))$ increases with increases in the cost of search, increases in the rate of interest, and with positive translations of the wage offer distribution. The effect of increases in the rate of job

offer arrivals and increases in the variance of the wage offer distribution on the hazard rate is ambiguous. Thus, ceteris paribus, increases in the cost of search, the rate of interest and positive translations of the wage offer distribution decrease the mean length of unemployment and result in unemployment duration distributions that are stochastically dominated by the predisplacement distributions.

If $r = 0$, straightforward manipulation of (1.2)' reproduces all of the preceding propositions except those for r and translations of the wage offer distribution. It is well known that if $r = 0$ unit translations of the wage offer distribution lead to unit increases in reservation wages. Thus translations of the wage offer distribution in this case produce no change in the hazard rate.

1.2 Relationship to Previous Discrete Time Models of Discrete Choice

Previous work in deterministic labor supply theory (e.g., Heckman and Willis, 1977; Heckman and MaCurdy; 1980, Heckman, 1981) estimates a discrete time analogue of the model described above. For a single spell of nonemployment, the decision to remain nonemployed is made by comparing a market wage offer X to reservation wage rV although a different theory is used to derive the reservation wage. Kiefer and Neumann (1979) have applied discrete time econometric models developed in the deterministic labor supply literature to the search unemployment problem.

The assumption used in previous work is that new wage offers (or in the labor supply theory, reservation wages, or both) arrive each time period. To focus on essential aspects of the comparison we assume that the reservation wage is nonstochastic, and the cdf of the independent wage offers is $F(X)$. Previous models produce the probability that

a nonemployment spell terminates after j periods as

$$P(j) = (F(rV))^{j-1} (1 - F(rV)).$$

Accepted wages are truncated from below by rV so that (1.5) is the density of these offers. Thus the joint density of duration times and accepted wages is

$$k(j,x) = [F(rv)]^{j-1} f(x) \qquad x \geq rV.$$

This approach is somewhat arbitrary because it is time unit dependent. To use it one must assume that wage offers come in at the rate of exactly one per period. (This is a crucial assumption in the Kiefer-Neumann analysis. See Appendix C.) The model developed in this paper assumes that wage offers arrive at random times. The cost of this generality is the introduction of parameters of the wage arrival function (λ).

1.3 Identification[1]

We assume the analyst has access to longitudinal data on N independent spells of unemployment. At this point we assume that all individuals have common structural parameters. The sampling frame is a fixed known time

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[1]Kiefer and Neumann (1979) have indirectly addressed this problem for the case of log normally distributed X in a discrete time search model with one wage offer received each period. They address the problem of identification in these models using standard sample selection bias methods. The analysis considered in this section is more general because it permits wage offers to arrive randomly, it is not specific to a log normal wage offer distribution, and because it utilizes crucial information overlooked in their analysis. For example, their analysis apparently implies that $r > 0$ is a necessary condition for identification. From their analysis it would appear that adding a wage arrival parameter λ to the model could make the model unidentified, especially if $r = 0$. Their analysis is misleading on important points.

frame of length $\bar{T}_u$. Some spells may be censored (so $t_u = \bar{T}_u$). At the end of the sampling period an unemployment spell may still be in progress. Thus for certain episodes we do not observe an accepted wage.

Our approach to identification is somewhat unusual in that it is nonparametric. We produce consistent estimators of the reservation wage and the distribution functions of accepted wages (x) and durations (t_u). We also ask under what conditions we can solve from conditional empirical distribution functions (which are pointwise consistently estimated except at points of discontinuity see, _e.g._, Billingsley, 1968) and the estimated reservation wage for the underlying structural parameters and distributions of interest. A crucial identification condition is a <u>recoverability condition</u>, not always satisfied, which enables the analyst to recover an untruncated distribution from a truncated distribution.

From a random sample of unemployment durations, possibly censored, it is possible to use a Kaplan-Meier estimator (see Kalbfleisch and Prentice, 1980, pp. 10-16) to consistently estimate the integrated hazard and hence the hazard (eq. (1.6)). It is thus possible to consistently estimate $h = \lambda(1-F(rV))$. A variety of alternative estimators could be used.[1] From duration data alone, it is not possible to separate λ from $(1-F(rV))$.

From data on accepted wage offers it is possible to directly estimate the reservation wage.[2] The density of accepted wage offers is given in

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[1] We note that there are better behaved estimators for the hazard than the one mentioned here. We use the estimator in our identification analysis only to indicate that in principle it is possible to estimate h non-parametrically. See the discussion in Section 1.4.

[2] This obvious and essential point has not hitherto been noted in the literature.

eq. (1.5). The smallest accepted wage (X_{min}) in a sample of size N has density

(1.7) $q(x_{min}) = N \left[\dfrac{f(x_{min})}{1-F(rV)}\right] \left[\dfrac{1-F(x_{min})}{1-F(rV)}\right]^{N-1}$

$$rV \leq x_{min} \leq \infty.$$

The limiting distribution of X_{min} (obtained by letting $N \to \infty$) places point mass at $x_{min} = rV$. "X_{min}" is a strongly consistent estimator of reservation wage rV. There are obviously many other strongly consistent estimators of rV (e.g. the second smallest accepted wage, etc.) The fact that the range of X depends on a parameter (rV) means that a standard regularity assumption is violated. We develop this point in the next section where specific estimation strategies for parametric models are discussed.

The empirical cdf of accepted wages converges pointwise (at all points of continuity) to the population cdf of accepted wages

$$F(x|x \geq rV) = \frac{F(x) - F(rV)}{1 - F(rV)}, \quad x \geq rV.$$

In light of the discussion in the preceding paragraph, rV can be consistently estimated. Provided that it is possible to recover the untruncated distribution $F(x)$ from the truncated distribution knowing the point of truncation, it is possible to estimate $F(x)$ from an estimate of $F(x|x \geq rV)$ and rV.

We define a distribution $F(x)$ to be recoverable from a truncated distribution with known point of truncation (rV) if knowledge of $F(x|x>rV)$ and rV implies that $F(x)$ is uniquely determined.

Provided that F(x) is recoverable, all of the parameters in equation (1.2) are identified provided that r is known. Thus if F(x) and rV are known, from the estimated hazard λ is known. (See eq. (1.6)). With λ known, F and rV can be inserted in (1.2) to estimate c.[1]

F(x) is not recoverable without maintaining some functional form assumption, and it is not recoverable for all functional forms. Two absolutely continuous distributions that produce the same truncated distribution with the same known points of truncation have densities that differ only by a linear transformation. If densities f(x) and f*(x) both generate the same truncated cdf, then f*(x) = bf(x) for x ≥ rV.

To show this note that if

$$F^*(x \mid x > rV) = \frac{F^*(x)-F^*(rV)}{1-F^*(rV)} = \frac{F(x)-F(rV)}{1-F(rV)} = F(x \mid x > rV)$$

for all x ≥ rV, then from absolute continuity

$$\frac{f^*(x)}{1-F^*(rV)} = \frac{f(x)}{1-F(rV)} \quad \text{for all } x \geq rV$$

so the densities must be proportional at all points of continuity of the distributions, i.e., f* = bf for x ≥ rV where $b = \frac{1-F^*(rV)}{1-F(rV)}$. Thus the distribution functions are related by F*(x) = a + bF(x) where a = 1 - b.[2]

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[1] If c is known a priori, it is possible (with known F and rV) to estimate r.

[2] In a discrete time search model with one wage offer assumed to arrive each period, we can estimate F(rV). In this case we can uniquely determine F (for F absolutely continuous) using the additional information that

$$F(rV) = k$$

where k and rV are known constants. Since we know the denominator of the conditional density, we can uniquely determine F and hence f. This is an essential feature in the Kiefer-Neumann analysis (see Appendix C).

Without imposing a parametric structure on $f(x)$, it is not possible
to determine the shape of $f(x)$ for values of x below rV. It is possible
to determine the shape of $f(x)$ for $x \geq rV$ (up to a scalar multiplication)
but not the mass above rV.

Without further information it is not possible to solve from the
truncated distribution and the known point of truncation for a unique
untruncated distribution. There are obviously many untruncated distri-
butions which can produce the same truncated distribution at a given
point of truncation. For this reason, a completely nonparametric approach
to identification is impossible. Unless a recoverability condition is
imposed, the structural duration model is not identified. (Precisely
the same statement holds for all econometric models for the analysis
of truncated data.)

It is sometimes possible to achieve recoverability by restricting
the true distribution $F(x)$ to be a member of a certain class of parametric
families. Thus if we require $F(x)$ and $F^*(x)$ to be normal distributions,
$F(x) = F^*(x)$ ($a = 0$ and $b = 1$). (This restriction does not deny that
some nonnormal F^* may also fit the truncated data.) Identification
through the use of functional form is not always possible.

We present an example in which the recoverability condition is
not met even if we impose the assumption that wage offers come from a
distribution with known functional form. Let wages be Pareto distributed

$$dF(x) = \phi x^{\beta} dx, \quad c_2 \leq x \leq \infty, \quad \beta \leq -2$$

$$\phi = \frac{-(\beta+1)}{(c_2)^{\beta+1}}$$

so

$$F(x|x > rV) = \frac{-(\beta+1)x^{\beta}}{(rV)^{\beta+1}}, \quad x \geq rV \geq c_2.$$

The parameter ϕ (or c_2) cannot be identified. Thus there are many Pareto distributions that fit the truncated wage data equally well.

To explore the consequences of the lack of recoverability in the Pareto case on the remaining parameters of the model, write (1.2) for the Pareto case as

$$c + rV = \left(\frac{\lambda\phi}{r} \right) \left(\frac{(rV)^{\beta+2}}{r(\beta+1)(\beta+2)} \right) .$$

The hazard is

$$h = \lambda(1-F(rV)) = \frac{-\lambda\phi}{(\beta+1)} (rV)^{\beta+1} .$$

"rV" is identified and so are β, $\lambda\phi$, and c. But obviously ϕ and λ cannot be separately identified (we can use the inequality $rV \geq c_2$ to produce an upper bound on c_2, an upper bound on ϕ and hence a lower bound on λ).

The fact that identification hinges on the functional form of the wage

offer distribution is an unsettling result but accords with economic

intuition. Without some restrictions imposed, it should not be possible

to distinguish a model with a lot of the mass in the wage offer distri-

bution near zero from a model with a low arrival rate for job offers,

and with little mass in the wage offer distribution near zero. This

point is discussed further in Section 2.

If wages are normally distributed, the recoverability condition

is satisfied. This fact is implicitly utilized in Amemiya (1973) and

Pearson (1903). The condition is also satisfied for many commonly utilized

distributions such as the exponential and log normal distributions.[1]

It is possible to test the concordance of any assumed functional

form for $F(x)$ with the data. Following Heckman (1976a) it is possible

to use a Kolmogorov-Smirnov test or chi-square test to test concordance

between the empirical counterpart of $F(x|x \geq rV)$ and a particular para-

metric cdf.[2] Thus the selection of a particular functional form need

not be an entirely arbitrary process. But the fact that a given functional

form is statistically concordant with the data does not imply that it

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[1] The identification analysis of Kiefer and Neumann (1979) based on a log normal distribution for wage offers apparently requires $r > 0$. Their model satisfies the recoverability condition. The assumption $r > 0$ is not needed to achieve model identification. Provided that R (in equation (1.2)') is non-negative, it is possible to repeat the analysis in the text for $r = 0$. Replacing rV in the text equations with R, it is possible to use accepted wage data to consistently estimate R using the minimum value of X in the sample. From the data on accepted wages it is possible to estimate the accepted wage distribution. Given the point of truncation, and satisfaction of the re-coverability condition, it is possible to estimate $F(X)$, hence $F(R)$, and λ. Using equation (1.2)' it is possible to consistently estimate c. For more discussion of the Kiefer-Neumann analysis see Appendix C.

[2] The KS test must be modified to correct for parameter estimation. See Durbin (1973) pp. 53-54.

is the only functional form consistent with the data. There is no statistical test for recoverability that can be based on the data generated by the model.

1.4 Estimation

The preceding section generates identification criteria by way of producing consistent nonparametric estimators. No claim was made there about the efficiency or asymptotic distribution of those estimators. These topics are more readily addressed in a parametric framework. In this section we examine the maximum likelihood estimator of the one spell search model in a parametric setting, and derive the appropriate asymptotic distribution.

Two new points arise. First, as is evident from equation (1.7), estimation is being considered in a non-regular setting because the lower limit of the accepted wage offer distribution depends on a parameter of the model (rV). Thus standard asymptotic distribution arguments will not apply (Cox and Hinkley, 1974, p. 112). Second, because we utilize a parametric framework, it becomes essential to explicitly account for censoring of duration spells.[1] If the sampling plan of the longitudinal data is such that spells of length greater than $\bar{t}_u$ are not observed, the density of t_u and x conditional on $t_u \leq \bar{t}_u$ is

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[1] The nonparametric Kaplan-Meier estimator can be applied to censored or uncensored data.

$$m(t_u, x \mid t_u \le \bar{T}_u) = \left[\frac{\lambda(1-F(rV)) \exp-\lambda(1-F(rV))t_u}{1 - \exp-\lambda(1-F(rV)\bar{t}_u)} \right] \left[\frac{f(x)}{1-F(rV)} \right]$$

where the denominator of the first term in brackets is the probability that $t_u \le \bar{t}_u$.

Let d denote an indicator function with

$d = 1$ if $t_u \le \bar{t}_u$

$d = 0$ otherwise.

Then the joint density of d, t_u and X is

$$m(t_u, x, d) = \left[f(x)\lambda \exp-\lambda(1-F(rV))t_u \right]^d \left[\exp-\lambda(1-F(rV))\bar{t}_u \right]^{1-d}. \quad (1)$$

The full economic model for $r > 0$ implies the following restrictions:

(1.8) $x \ge rV \ge 0$

$$rV + c = \frac{\lambda}{r} \int_{rV}^{\infty} (x-rV) \, dF(x). \quad (2)$$

In the remainder of this section we write the distribution function of wage offers as $F(x\mid\theta)$ to explicitly demonstrate the dependence of $F(x\mid\theta)$ on a finite dimensional vector of bounded parameters (θ). We assume that $F(x\mid\theta)$ is recoverable (in the sense of section 1.3) and hence that θ is identified. We assume that r is known.

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[1] In forming this density we use the fact that the probability $d=0$ is the same as the probability that t_u exceeds $\bar{t}_u (=\exp-(1-F(rV))\bar{t}_u)$. The probability that t_u is less than $\bar{t}_u$ is $(1-\exp-(1-F(rV))\bar{t}_u)$.

[2] The second constraint for the case $r = 0$ is equation (1.2)'. In that notation, the first constraint is $x \ge R \ge 0$.

The sample log likelihood function (with individual subscripts suppressed) for a longitudinal sample of N independent individuals is

(1.9) $\quad \mathcal{L} \quad = \quad \Sigma \ln m(t_u, x, d)$

$\quad\quad\quad\quad = \quad (\Sigma d)\ln \lambda + \Sigma d \ln f(x|\theta) - \lambda(1-F(rV|\theta))\Sigma t_u$

where $t_u = \bar{t}_u$ for the censored observations.

Structural estimation of the model requires maximizing (1.9) incorporating the economic restrictions in (1.8). There are many possible parameterizations of the likelihood function. The most analytically convenient one treats rV as an explicit parameter along with θ and λ using (1.8) to solve for c. This parameterization does not force c to be positive and so provides a test of the model. Note that for the model to make statistical sense, it is required that $\lambda > 0$. This constraint is automatically imposed in the estimation as we demonstrate below.

The maximum likelihood estimator has a simple structure. Denoting the maximum likelihood estimator by "^", $r\hat{V} = x_{min}$ where x_{min} is the minimum accepted wage observed in the sample of job takers (for whom d=1). That this is the mle estimator is verified by noting that $\mathcal{L}$ is monotonically increasing in rV so that the first constraint in (1.8) is always effective at the upper limit.

This estimator is strongly consistent. Producing the asymptotic distribution theory for the estimator is a more delicate matter. As is well known (See Galambos, 1978, p. 71) for a given $F(x|\theta)$ there may exist no norming factors such that $a(n_1)X_{min} + b(n_1)$ converges to a distribution where $a(n_1)$ and $b(n_1)$ are functions of $n_1(=\Sigma d)$. If such factors exist, the asymptotic distribution is one of two possible functional

forms (See Galambos, pp. 56-57).[1] The existence and functional

form of the limiting distribution of X_{min} is critically dependent

on the functional form of $F(x|\theta)$ although the strong consistency

of the estimator does not depend on this functional form.

The following theorem establishes a general condition under which

$\sqrt{N}(X_{min} - rV)$ has a degenerate distribution.

Thm. 1. Define $z = \sqrt{N}(X_{min} - rV)$. If and only if

$$(1.10) \qquad \lim_{N \to \infty} \left[\frac{1 - F\left(rV + \frac{z}{\sqrt{N}} | \theta\right)}{1 - F(rV|\theta)} \right]^N \to 0 \qquad \text{for } z > 0,$$

$z = \sqrt{N}(X_{min} - rV)$ has a degenerate distribution at $z = 0$.

Proof. From (1.7) and integration

$$F(x_{min}) = 1 - \left[\frac{1 - F(x_{min}|\theta)}{1 - F(rV|\theta)} \right]^N.$$

Thus the cdf of z say $K(z)$ is

$$K(z) = 1 - \left[\frac{1 - F(rV + \frac{z}{\sqrt{N}} | \theta)}{1 - F(rV|\theta)} \right]^N.$$

Then, we have $\lim K(z) = 1$, $z > 0$ if and only if

$$\lim_{N \to \infty} \left[\frac{1 - F(rV + \frac{z}{\sqrt{N}} | \theta)}{1 - F(rV|\theta)} \right]^N \to 0, \ z > 0.$$

$$\text{QED.}$$

---

[1] The forms for the cdfs are (See Galambos)

$$L_2 = 1 - \exp(-x^\gamma) \qquad x > 0$$

or

$$L_3 = 1 - \exp(-e^x).$$

For the relevant discussion see Galambos (1978), where the $a(n_1)$ and $b(n_1)$

functions are produced for specific functional forms.

For example, if $F(x|\theta) = 1 - e^{-\theta x}$, $\theta > 0$, the limit in (1.10) is achieved so that $\sqrt{N}\ (X_{min} - rV)$ has a degenerate asymptotic distribution. In fact $N(X_{min} - rV) \sim 1 - e^{-\theta(X_{min} - rV)}$ and convergence in distribution is at rate N.

Violation of condition (1.10) is unusual as demonstrated in the next theorem.

Theorem 2. $F'(rV|\theta) = 0 = f(rV|\theta)$ is a necessary condition for (1.10) to be violated for F at least twice continuously differentiable with a bounded second derivative.

Proof:

$$N \ln \left[\frac{1 - F(rV + \frac{z}{\sqrt{N}}|\theta)}{1 - F(rV|\theta)} \right]$$

$$\doteq N \left[1 - \frac{f(rV|\theta)}{1-F(rV|\theta)} \frac{z}{\sqrt{N}} + \frac{1}{2} \frac{f'(rV|\theta)}{1-F(rV|\theta)} \frac{z^2}{N} + o(\frac{1}{N}) \right]$$

If $f(rV|\theta) = 0$

$$\lim_{N\to\infty} N \left[\frac{1 - F(rV + \frac{z}{\sqrt{N}}|\theta)}{1 - F(rV|\theta)} \right] = \frac{1}{2} \frac{f'(rV|\theta)}{1-F(rV|\theta)} z^2$$

so condition (1.10) is violated.   QED.

The condition $f(rV|\theta) = 0$ is not likely to be satisfied for most standard distributions.

The thrust of the two theorems is that in cases that are likely to arise in applied work, $\sqrt{N}\ (X_{min} - rV)$ has a degenerate distribution. This, in turn, implies that if $\hat{rV}$ is inserted in likelihood (1.9) we

may treat $r\hat{V}$ as if it is rV in determining the ($\sqrt{N}$) asymptotic distributions of the remaining parameters.[1]

Conditional on $r\hat{V}$, the likelihood equation for λ is

$$\mathcal{L}_\lambda = C = \frac{(\Sigma d)}{\lambda} - (1 - F(r\hat{V}|\theta))\Sigma t_u$$

so

$$\hat{\lambda} = \frac{(\Sigma d)}{(1 - F(r\hat{V}|\theta))(\Sigma t_u)} .$$

The equation for θ is

$$\mathcal{L}_\theta = 0 = \Sigma^d \frac{f_\theta(x|\theta)}{f(x|\theta)} + \lambda F_\theta(r\hat{V}|\theta)\Sigma t_u$$

which can be simplified to

$$0 = \Sigma^d \frac{f_\theta(x|\hat{\theta})}{f(x|\hat{\theta})} + \frac{(\Sigma d) F_\theta(r\hat{V}|\hat{\theta})}{1 - F(rV|\hat{\theta})} .$$

$\hat{\lambda}$ is always nonnegative. Conditional on $r\hat{V}$, the estimators are consistent and asymptotically normally distributed provided that the information matrix is of full rank. Proofs of the assertions are trivial and hence are deleted.

We state without proof.

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[1] In a valuable paper on frontier production theory, Greene (1980) invokes conditions that ensure that (1.10) is violated and that standard asymptotic theory can be applied. He demonstrates that standard regularity conditions need not be satisfied in order to produce standard asymptotic distribution results. His results, while very useful in his context, are not of direct use here because to satisfy his conditions we would have to assume $f(x|\theta) = 0$ over the economically interesting interval for x.

Theorem 3. If condition (1.10) is met,

$$\sqrt{N} \begin{pmatrix} \hat{\lambda} - \lambda \\ \hat{\theta} - \theta \end{pmatrix} \sim N\left(0, I^{-1}(\hat{rV})\right)$$

where

$$I(\hat{rV}) = -E \frac{\partial^2 \mathcal{L}(\hat{rV})}{\partial \psi \partial \psi'} = -E \frac{\partial^2 \mathcal{L}(rV)}{\partial \psi \partial \psi'}$$

where

$$\psi = \begin{pmatrix} \lambda \\ \theta \end{pmatrix}.$$

With estimates of rV, θ and λ, we may solve for c from the second equation of (1.8). We may use the delta method to obtain the sampling distribution for c (Bishop, Fienberg and Holland, 1975, p. 486). Assuming that $\sqrt{N}$ ($X_{min} - rV$) is degenerate, $\hat{rV}$ contributes only to the mean of the sampling distribution of c. Thus

$$\hat{c} = \frac{\hat{\lambda}}{r} \int_{\hat{rV}}^{\infty} (x - \hat{rV}) \, dF(x|\hat{\theta}) - \hat{rV}$$

and

$$\sqrt{N} (\hat{c} - c) \sim N(0, \sigma_c^2)$$

where σ_c^2 is obtained by the usual Taylor series development and the covariance of $\sqrt{N}$ ($\hat{c} - c$) with the other parameters is obtained in the usual way.

A simple example will help to clarify ideas. Suppose the sampling frame is such that there are no censored observations ($\bar{t}_u = \infty$). Suppose further that wages are exponentiably distributed so

$$(1.11) \qquad dF(x|\theta) = \theta e^{-\theta x} dx, \quad \theta > 0.$$

With a zero rate of interest and Poisson arrival parameter λ, simple substitution in (1.2)' confirms that the reservation wage R satisfies

$$(1.12) \qquad R = (\frac{-1}{\theta}) \ln(\frac{C\theta}{\lambda}).$$

For the search problem to be economically meaningful we require $R > 0$ so that $\frac{C\theta}{\lambda} < 1$ since θ, λ and C are all positive. [1]

In a sample of size N, the density of the minimum accepted wage offer X_{min} is

$$(1.13) \qquad q(x_{min}) = N\theta e^{-N(x_{min} - R)\theta}, \quad x_{min} \geq R$$

with mean

$$E(X_{min}) = \frac{N\theta R + 1}{N\theta} = R + \frac{1}{N\theta}.$$

Thus X_{min} is an upward biased but consistent estimator for R.

The log likelihood function (1.9) with $\Sigma d = N$ is

$$\mathcal{L} = N \ln \theta - \theta\Sigma x + N \ln \lambda - \lambda e^{-\theta R}\Sigma t.$$

The maximum likelihood estimators are achieved from the following procedure. First estimate R by x_{min}. $(\hat{R} = x_{min})$. Then maximize the concentrated likelihood function $\mathcal{L}(\hat{R}) = N \ln \theta\lambda - \theta\Sigma x - \lambda e^{-\theta x_{min}}\Sigma t$. where x_{min} is substituted for R in the previous expression. The roots of the conditional maximum likelihood equations obtained from $\mathcal{L}(x_{min})$ are

$$\frac{1}{\theta} - \frac{\Sigma x}{N} + x_{min} = 0$$

$$\frac{1}{\lambda} - \frac{\Sigma t}{N} e^{-\hat{\theta} x_{min}} = 0.$$

$\hat{\theta}$ and $\hat{\lambda}$ are consistent for θ and λ respectively, and both are biased. The exact bias of $1/\hat{\theta}$ for $1/\theta$ can be computed since

_____

[1] Note that x is interpreted as a lump sum undiscounted value of the job.

$$E\left(\frac{1}{\hat{\theta}}\right) = \frac{1}{\theta} + \frac{1}{N\theta} \; .$$

The bias is of order N^{-1}. It can also be shown that the bias of $1/\hat{\lambda}$ for $1/\lambda$ is of order $1/N$.[1]

A consistent estimator of c is obtained by substituting x_{min} for R and $\hat{c}$ and $\hat{\theta}$ for c and θ respectively in (1.12). Thus

$$\hat{c} = \frac{\hat{\lambda}}{\hat{\theta}} \; e^{-\hat{\theta} x_{min}}$$

A norming factor of N is required to produce a nondegenerate asymptotic distribution for x_{min}. With this factor

$$N(x_{min} - R) \sim \theta e^{-\theta \psi}, \; \psi \geq 0 \; .$$

Because $\sqrt{N} \; (x_{min} - R)$ is a degenerate random variable,

$$\sqrt{N} \begin{pmatrix} \hat{\theta} - \theta \\ \hat{\lambda} - \lambda \end{pmatrix} \sim \; n \, (0, I^{-1})$$

where
$$I^{-1} = - \begin{pmatrix} \frac{1}{\theta^2} + R^2 & -\frac{R}{\lambda} \\ -\frac{R}{\lambda} & \frac{1}{\lambda^2} \end{pmatrix}^{-1} = \begin{pmatrix} \theta^2 & R\theta^2 \lambda \\ R\theta^2\lambda & \lambda^2 + \lambda^2\theta^2 R^2 \end{pmatrix} .$$

---

[1] An unbiased estimator of $1/\theta$ is
$$\frac{1}{\hat{\hat{\theta}}} = \frac{N\left(\frac{\Sigma x}{N} - x_{min}\right)}{N-1}$$

so that

$$(2N-1)\left(\frac{1}{\hat{\hat{\theta}}} \Big/ \frac{1}{\theta}\right) \sim \chi^2 \text{ with } 2(N-1) \text{ degrees of freedom.}$$

Thus $\hat{\theta}$ and $\hat{\lambda}$ are asymptotically positively correlated. The information

matrix may be consistently estimated replacing parameters with maximum

likelihood estimates. The asymptotic distribution for $\sqrt{N}$ $(\hat{c}-c)$

can be derived from the delta method using the joint asymptotic

distribution for $\hat{\theta}$ and $\hat{\lambda}$ and the fact that $\sqrt{N}$ $(x_{min} -R)$ is degenerate.[1]

For a comparison between the approach to structural estimation based on

maximum likelihood which we use and other approaches, see Appendix C.

1.5. <u>Accounting for Population Dispersion in the Parameters of the Model</u>

We have thus far assumed that all agents in our samples

have identical values of λ, c, r and θ. There are plausible reasons why

values of those parameters might vary among members of the population.

In many economic models of equilibrium price distributions, dispersion in c (or

some other parameter) is required to produce equilibrium. Failure to account for

such dispersion can produce badly biased estimates of the parameters

of structural duration models (Silcock, 1954; Blumen, Kogan and McCarthy,

1955). This is the problem of "heterogeneity."

In principle, each parameter of the one state search model can be

written as a function of observed and unobserved variables. The parameters

---

[1] An estimator such as $\hat{rV}$ that is based on an extreme observation
in a sample is obviously quite sensitive to measurement error in the
x data. Since any fixed number of extreme observations (say the first
up to the kth) are consistent estimators for rV, a consistent estimator
for rV that is less sensitive (in an imprecisely defined way) to measure-
ment error is an average of the lowest k observations. Greene's
estimator (1980) in a related problem is also worthy of exploration:
compute $\hat{rV}$ from adjacent values of the lowest observations of x that
are "close". See the discussion of measurement error in Section 1.5B below.

associated with the observed variables in these functions can be estimated. Unobserved variables can be integrated out using distributions whose parameters can be estimated. This approach is used in many studies of labor force dynamics (Heckman and Willis, 1975, 1977; Nickell, 1979; Heckman, 1981.)

A practical problem with this solution is the selection of particular functional forms for use in estimation. Except for occasional qualitative guidelines, economic theory offers little guidance. It is silent on the topic of the correct specification of functional forms for the distributions of unobservables.

This would not be a serious problem if estimates of key parameters of the model were "relatively" insensitive to assumptions made about specific functional forms. In fact, the available evidence (Heckman and Singer, 1981a, b) suggests the opposite. Estimates of key parameters are very sensitive to the choice of particular functional forms.

The situation is not entirely hopeless. Heckman and Singer (1981, 1982) present a computationally feasible nonparametric estimator for the distribution functions of unobservables, so that at least one aspect of arbitrariness in model specification can be eliminated with their methods. Nonetheless, a considerable amount of arbitrariness remains, and this arbitrariness vitally affects the inference from the structural models.

These problems are more troublesome than recent analyses indicate is the case. In this subsection we make a first attempt at clarifying the issues that must be addressed in order to account for population dispersion in parameters. We also offer some solutions. What follows is only the first and (we hope) not the last word on these problems.

It is analytically useful to distinguish two cases. (1) The case in which population heterogeneity arises solely from dispersion in observed variables and (2) the case in which the heterogeneity arises from unobserved variables. We treat these two cases, starting with the first. In both cases we assume a parametric distribution of wage offers $F(X|\theta)$ that satisfies the recoverability condition. A fully general analysis of both cases is not attempted, but we indicate the gaps that remain to be filled (of which we are aware).

1.5.A. Observed Heterogeneity

We first write $\lambda = \lambda(Z_\lambda \beta_\lambda)$; $\theta = \theta(Z_\theta \beta_\theta)$ and $c = c(Z_c \beta_c)$ to indicate the dependence of λ, θ and c on explanatory variables. From equation (1.8), rV is a function of Z and all the β vectors. The density for t_u, X and d conditional on $Z = (Z_\lambda, Z_\theta, Z_c)$ is

$$(1.14) \qquad m(t_u, x, d|Z) = [f(x|\theta)\lambda]^d \exp-[\lambda(1-F(rV|\theta))t_u]$$

where

$$(1.15) \qquad x \geq rV \geq 0 \quad \text{for each value of Z}$$

and

$$(1.16) \qquad c = \frac{\lambda}{r} \int_{rV}^{\infty} (X - rV)\,dF(X|\theta) - rV,$$

where it is understood that λ, θ and c are functions of exogenous variables, and t_u denotes the duration of all measured spells including the censored spells. r is assumed to be known.

From equation (1.16) we may solve for rV as a function of c, λ, r and θ,

$$rV = rV(Z_\lambda \beta_\lambda, Z_\theta \beta_\theta, Z_c \beta_c, r).$$

The reservation wage is monotonic in the cost of search c $(=c(Z_c \beta_c))$.

Using the inequalities in (1.15) that must be satisfied for each observation, the log likelihood is (suppressing subscripts)

$$(1.17) \quad \pounds = \Sigma d \ln \lambda + \Sigma d \ln F(x|\theta) - \Sigma \lambda (1 - F(rV|\theta)) t_u$$

$$+ \Sigma \mu (x - rV(\lambda, \theta, c, r)) + \Sigma \phi (rV(\lambda, \theta, c, r))$$

where $\theta = \theta(Z_\theta \beta_\theta)$, $\lambda = \lambda(Z_\lambda \beta_\lambda)$ and $c = c(Z_c \beta_c)$ and where the multipliers μ and ϕ are defined for each observation.[1] The final two sets of constraints arise as a consequence of inequality (1.15) that must be satisfied for each observation. These constraints are a vital source of identification in this model and cannot be ignored in securing structural estimates.

Provided that the multipliers are well defined (see the footnote below) the first order conditions for β_θ, β_λ and β_c are

---

[1] The existence of these multipliers and the quasi-saddle point characterization of the optimum used in the text follows if rV and $x - rV$ as functions of β satisfy the Arrow-Hurwicz-Uzawa conditions (see Takayama, 1974, pp. 93-94). Their rank condition is likely to be satisfied in "large enough" samples. We have not investigated the restrictions these conditions place on our choice of c, λ and θ functions although this would be a potentially fruitful topic.

$$(1.18a) \quad \pounds_{\beta_\theta} = o = \sum \left\{ \left(d \frac{\partial \ln F(x|\theta)}{\partial \theta} \right) + \lambda \left(\frac{\partial F(rV|\theta)}{\partial rV} \frac{\partial rV}{\partial \theta} + \frac{\partial F(rV|\theta)}{\partial \theta} \right) t_u \right.$$

$$\left. + (\phi - \mu) \frac{\partial rV}{\partial \theta} \right\} \frac{\partial \theta}{\partial \beta_\theta}$$

$$(1.18b) \quad \pounds_{\beta_\lambda} = o = \sum \left\{ \frac{d}{\lambda} - (1 - F(rV|\theta)) t_u + \lambda \frac{\partial F(rV|\theta)}{\partial rV} \cdot \frac{\partial rV}{\partial \lambda} + (\phi - \mu) \frac{\partial rV}{\partial \lambda} \right\} \frac{\partial \lambda}{\partial \beta_\lambda}$$

$$(1.18c) \quad \pounds_{\beta_c} = o = \sum \left\{ \lambda \frac{\partial F(rV|\theta)}{\partial rV} t_u + (\phi - \mu) \right\} \frac{\partial rV}{\partial c} \frac{\partial c}{\partial \beta_c} \quad .$$

A critical feature of this optimization problem is revealed in condition (1.18c). Note that

$$\frac{\partial F(rV|\theta)}{\partial rV} \frac{\partial rV}{\partial c}$$

is always nonpositive and for most parametric problems is negative.[1] If constraint (1.15) is ignored in solving for β_c (so we assume $\phi = \mu = 0$), the likelihood function possesses no interior maximum with respect to β_c unless we impose an arbitrary nonlinearity that guarantees that c is not monotonic in β_c and that bounds c from below. For example, if c is a constant, a maximum likelihood estimator of c that ignores (1.15) sets c at its lowest possible value.

A general analysis of identification and distribution theory is a task for the future. We make some progress by assuming that the number of distinct Z vectors is finite and equal to K and that the population covariance matrix of Z is of full rank. This is consistent with "fixed in repeated samples" sampling schemes or with the Z vectors selected by a finite K state

---

[1] λ is positive, $\frac{\partial F(rV|\theta)}{\partial rV}$ is nonnegative and $\frac{\partial rV}{\partial c}$ is negative. The last assertion can be proved by differentiating (1.16) with respect to c.

irreducible Markov chain so that all states are recurrent. This assumption is critical in the ensuing analysis. If it is not invoked, we are unable to produce consistent estimators for the model although we speculate below on how this might be done. We denote the population proportion of the exogenous variables of type k by P_k, $0 < P_k < 1$.

By analogy with the analysis in Section 1.4 we may estimate rV_k for each $k = 1,\ldots,K$. For $N \to \infty$ so $P_k N \to \infty$, these estimators are strongly consistent. Insert these estimators into

$$\tilde{\mathcal{L}} = \Sigma d(\ln \lambda + \ln f(x|\theta)) - \Sigma \lambda(1 - F(rV|\theta))t_u$$

in place of rV (associating $\hat{rV}_k$ with observations of type k) and maximize with respect to β_θ and β_λ. Provided the matrix of second partials of $\tilde{\mathcal{L}}$ (with respect to β_λ and β_θ) is nonsingular, these equations may be solved uniquely for β_λ and β_θ and provided condition (1.10) is met for each k

$$\sqrt{N} \begin{pmatrix} \hat{\beta}_\lambda - \beta_\lambda \\ \hat{\beta}_\theta - \beta_\theta \end{pmatrix} \sim N(0, \mathcal{I}^{-1})$$

where $\mathcal{I}^{-1}$ is minus the inverse matrix of the expectation of the second partials of the log likelihood. Estimates of β_c are obtained by solving c_k from equation (1.16) and estimating a nonlinear regression of the $\hat{c}_k$ on $c(Z_c \beta_c)$. If the model is of full rank (the Z_c covariance matrix is positive definite) β_c is identified and its asymptotic distribution can be produced by generating the asymptotic distribution of c_k by the delta method, as before.

The key requirement is that the matrix of second partials of $\mathcal{L}$ with respect to β_λ and β_θ be of full rank. Verifying this condition in practice requires a case by case analysis for each choice of $f(X|\theta)$.

For the sake of specificity assume that $f(X|\theta) = \theta e^{-\theta X}$. We adopt the specification of the example presented in Section 1.4 with $r = 0$. As is done there, we ignore censored observations. We further assume that

(1.19) $\qquad c = \exp(Z_c \beta_c) \qquad \theta = \exp(Z_\theta \beta_\theta) \qquad \lambda = \exp(Z_\lambda \beta_\lambda).$

This parameterization imposes the required positivity for these parameters.

The log likelihood for this model is

(1.20) $\qquad \mathcal{L} = \Sigma d(Z_\lambda \beta_\lambda) + \Sigma d(Z_\theta \beta_\theta - \exp(Z_\theta \beta_\theta)x)$

$$- \Sigma \exp(Z_\lambda \beta_\lambda)(\exp(-rV_k\, e^{Z_\theta \beta_\theta})t_u).$$

where

(1.21) $\qquad rV_k = -e^{-X_\theta \beta_\theta}(Z_{c_k}\beta_c + Z_{\theta_k}\beta_\theta - Z_{\lambda_k}\beta_k) \geq 0,$

and where Z_{c_k}, Z_{θ_k} and Z_{λ_k} are values of the Z vectors for population type k.

For each type k we estimate the reservation wage by

$\hat{rV}_k = \min \{x_{ik}\}_{i=1}^{N_k}$ where x_{ik} is the ith observation on accepted wages for type k. These estimators are strongly consistent for rV_k and

$\lim_{N \to \infty} \sqrt{P_k N} (\hat{rV}_k - rV_k)$ is a degenerate random variable.

The roots of $\tilde{\mathcal{L}}$ with respect to β_θ and β_λ are

$$0 = \frac{\partial \mathcal{L}}{\partial \beta_\theta} = \Sigma Z_\theta - \Sigma Z_\theta e^{Z_\theta \beta_\theta}x + \Sigma(e^{Z_\lambda \beta_\lambda}t)\hat{rV}_k\, e^{-(e^{Z_\theta \beta_\theta})\hat{rV}_k}\, e^{Z_\theta \beta_\theta}$$

$$0 = \frac{\partial \mathcal{L}}{\partial \beta_\lambda} = \Sigma Z_\lambda - \Sigma Z_\lambda \left(e^{Z_\lambda \beta_\lambda} e^{-(e^{Z_\theta \beta_\theta}) \hat{rV}_k} \right) \dot{t}_u \quad .$$

As $N \to \infty$, the expectation of these first partials is zero at the true parameter values.

Conditional on $\hat{rV}_k$, minus the expectation of the matrix of second partials of the log likelihood is (letting $\beta = (\beta_\theta \beta_\lambda)$)

$$(1.22) \quad I = E\left(-\frac{\partial^2 \mathcal{L}(rV_k)}{\partial \beta \partial \beta'} \right) = \begin{pmatrix} \Sigma Z_\theta Z_\theta' (1 + (Z_c \beta_c + Z_\theta \beta_\theta - Z_\lambda \beta_\lambda)^2) & \cdot \\ \Sigma Z_\lambda Z_\theta' (Z_c \beta_c + Z_\theta \beta_\theta - Z_\lambda \beta_\lambda) & \Sigma Z_\lambda Z_\lambda' \end{pmatrix} \quad .$$

Note that $Z_c \beta_c + Z_\theta \beta_\theta - Z_\lambda \beta_\lambda \leq 0$ since $rV > 0$ (see equation (1.15)).

Even if $Z_\theta = Z_\lambda = Z_c = \bar{Z}$, this matrix is nonsingular provided that $\Sigma \bar{Z}\bar{Z}'$ is nonsingular. This follows from the matrix Cauchy-Schwartz inequality. Thus, even if the same variables appear in the c, λ and θ functions, it is possible to identify β_λ, β_θ and β_c.

To estimate β_c, take the estimated β_θ, β_λ and $\hat{rV}_k$ and form the left-hand side of the function

$$-\hat{rV}_k e^{Z_{\theta k} \hat{\beta}_\theta} - Z_{\theta k} \hat{\beta}_\theta + Z_{\lambda k} \hat{\beta}_\lambda = Z_c \beta_c \quad .$$

The distribution of the left-hand side can be derived from the delta method. Use GLS to estimate β_c. To identify β_c uniquely, it is required that the rank of $\Sigma Z_c Z_c'$ exceed the number of elements in β_c. A necessary condition is that K not be less than the number of elements in β_c.

Note that this procedure does not in general maximize the likelihood (1.17). Moreover it is wasteful in information. If the number of parameters in β_c is less than K, in general fewer than K of the estimated reservation wages are required to estimate β_c.

A second round iteration of the procedure just presented produces estimators with a covariance matrix no longer than the one produced by the method just presented.

The proposed iteration sequence operates by taking estimates of β_c, β_λ and β_θ from the first round procedure and forming rV_k for each type k using equation (1.16). For each k, use the minimum of rV_k so formed and $\hat{rV}_k$. Insert these values into $\tilde{\mathcal{L}}$ and obtain estimates of β_λ and β_θ as before. Using the second round estimated reservation wages and the estimates of β_λ and β_θ obtained on the second round, repeat the nonlinear regression procedure to estimate β_c. Continue iteration until convergence. In the case in which the number of parameters in β_c is the same as K, in general the iteration cycle just described will produce the same final estimates of β as used in the initial estimates because none of the reservation wage information is redundant.

For the case of a general distribution of Z, the likelihood and its roots are given in (1.17) and (1.18). The derivation of the asymptotic properties of the maximum likelihood estimator in the general case is a task for the future. We offer some conjectures on this problem in Appendix A where we make some progress on the problem for certain cases of interest.

1.5.B. Unobserved Heterogeneity[1]

Extending the analysis to a case in which population heterogeneity also arises from unobserved variables is in principle straightforward. When the models are identified the appropriate asymptotic distribution theory is much simpler than in the models of the preceding subsection. The practical problem is to decide where in the model to introduce the population heterogeneity. In principle we should allow for such hetero-geneity in the c, λ and θ functions so $c = c(Z_c \beta_c, \varepsilon_c)$, $\lambda = \lambda(Z_\lambda \beta_\lambda, \varepsilon_\lambda)$, $\theta = \theta(Z_\theta \beta_\theta, \varepsilon_\theta)$ where $\varepsilon = (\varepsilon_c, \varepsilon_\lambda, \varepsilon_\theta)$ is a vector of random variables with cdf $G(\varepsilon|\eta)$ where η is a vector of parameters. For simplicity we assume that c, λ and θ are monotone increasing functions of $\varepsilon_c, \varepsilon_\lambda$, and ε_θ respectively.

The reservation wage function is defined as

$$rV = rV(c, \theta, \lambda, r)$$

where c, λ, θ are functions of ε_c, ε_λ and ε_θ respectively. In the ensuing analysis it is convenient to work with a normalized cdf

$$G^*(\varepsilon|\eta) = \frac{G(\varepsilon|\eta)}{\int_{\{\varepsilon|rv>0\}} dG(\varepsilon|\eta)} \qquad \{\varepsilon|rV > 0\}$$

where $\{\varepsilon|\eta \geq 0\}$ is the set of values of ε such that the agent participates in the labor force. The probability that a spell lasts more than t_u periods conditional on c, λ, θ is

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[1] Conversations with T. Coleman and B. Payner clarified the analysis presented in this section.

$$P(T_u > t_u | c, \lambda, \theta) = \exp -\lambda[1 - F(rv|\theta)]t_u \quad .$$

Integrating out $\varepsilon = (\varepsilon_c, \varepsilon_\lambda, \varepsilon_\theta)$, using the information that $rV \geq 0$, yields

$$(1.24) \qquad P(T_u > t_u) = \int\limits_{\{\varepsilon | rV > 0\}} \exp -\lambda[1 - F(rV|\theta)]t_u \, dG^*(\varepsilon|\eta) \quad .$$

To reduce notational complexity we suppress the conditioning set of exogenous variables. The density of accepted wages conditional on c, λ, θ is

$$\frac{f(x|\theta)}{1-F(rV|\theta)} \qquad x \geq rV \quad .$$

Integrating out ε, the density of accepted wages is

$$(1.25) \qquad \int\limits_{\{\varepsilon | x \geq rV \geq 0\}} \frac{f(x|\theta)}{1-F(rV|\theta)} \, dG^*(\varepsilon|\eta) \quad .$$

The joint density of x, t_u given $d = 1$ and c, λ, θ is, for a sampling frame of length $\bar{t}_u$

$$m(t_u, x | d = 1) = \frac{\lambda f(x|\theta) \exp -\lambda[1-F(rV|\theta)]t_u}{1-P(T_u < \bar{t}_u | c, \lambda, \theta)} \quad .$$

Integrating out ε, the joint density of x and t_u given $d = 1$ is

$$(1.26) \quad m^*(t_u, x | d_u = 1) = \frac{\int\limits_{\{\varepsilon | x \geq rV \geq 0\}} f(x|\theta) \exp - [1-F(rV|\theta)]t_u \, dG^*(\varepsilon|\eta)}{1-P(T_u < \bar{t}_u)} \quad .$$

Using (1.24) and (1.26) the joint density of t_u, x and d is

$$(1.27) \quad m^*(t_u, x, d) = \left\{ \int\limits_{\{\varepsilon | x \geq rV \geq 0\}} \lambda f(x|\theta) \exp -\lambda[1-F(rV|\theta)]t_u \, dG^*(\varepsilon) \right\}^d$$

$$\cdot \left\{ \int\limits_{\{\varepsilon | rV \geq 0\}} \exp -\lambda(1-F(rV))\bar{t}_u \, dG^*(\varepsilon|\eta) \right\}^{1-d} \quad .$$

The likelihood function for duration of unemployment and accepted wages is defined as the product of densities (1.27).[1] Provided the model is identified, maximum likelihood estimators of β and η are consistent and asymptotically normally distributed provided standard conditions on the regressors (Z) are assumed (see e.g. Jennrich, 1969). Because "rV" is a random variable, the appropriate asymptotic distribution theory is much simpler than the distribution theory required to analyze the models presented in previous sections of this paper. This is so because in the present model the range of the random variable X does not depend on a parameter of the model.

The crucial identifying role played in the preceding section by the restriction that X must exceed the deterministic reservation wage (equation (1.21)) is played in the current model by a restriction on the range of unobservables

(1.28) $$\{\varepsilon \mid 0 \leq rV(c,\lambda,\theta,r) \leq x\}$$

that must be satisfied for all observations for which a completed unemployment spell and accepted wage are observed.

To demonstrate how (1.28) is used to achieve identification, assume $\varepsilon_\lambda = \varepsilon_\theta = 0$. Further assume $c = c(Z_c\beta_c + \varepsilon_c)$. Denote by $G_c^*(\varepsilon_c \mid \eta_c)$ the cdf of ε_c which depends on parameter vector η_c. To simplify the argument

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[1] Note that we could in principle exploit the information that individuals are out of the labor force. Density (1.27) is conditional on labor force participation. The modification of the analysis to incorporate information on non-participants is straightforward. Obviously, use of the additional information will improve the efficiency of the estimators.

assume the sampling frame is long enough that there are no censored observations (d = 1).

The log likelihood for the model is

$$(1.29) \qquad \mathcal{L} = \Sigma \int_{\{\epsilon_c | x \geq rV \geq 0\}} \lambda f(x|\theta) \exp -\lambda(1-F(rV|\theta)) t_u \, dG_c^*(\epsilon_c|\eta_c) .$$

The likelihood is not monotonic in $Z_c\beta_c$. This is confirmed by direct differentiation of (1.29). The intuition underlying this result is given here rather than the direct formal argument which is both tedious and unilluminating. The key idea is that β_c shifts both rV <u>and the admissible range of the unobservable ϵ_c</u>.

The kernel of the integral in (1.29) is monotone decreasing in $Z_c\beta_c$ because rV is monotone decreasing in c (and hence $Z_c\beta_c$) and because the kernel is monotone increasing in rV. For each value of x, λ, θ and η_c, (1.28) defines an admissible region of ϵ_c. In general, both the location and length of the admissible region change as $Z_c\beta_c$ and the other parameters are varied. For the special functional form assumed here ($c = c(Z_c\beta_c + \epsilon_c)$) for each x (and for fixed values of θ and λ) the admissible region for ϵ_c is connected and of the same length for different values of $Z_c\beta_c$. However, the position of the interval varies as $Z_c\beta_c$ varies, shifting to the left as $Z_c\beta_c$ increases. For fixed values of the other parameters (including η_c), increasing $Z_c\beta_c$ shifts the admissible ϵ_c interval to the

left. As $Z_c \beta_c$ increases the likelihood must eventually decrease. In the limit as $Z_c \beta_c \to \infty$, holding the other parameters fixed, the likelihood diverges to minus infinity as the integrals inside the logarithms of (1.29) vanish. A parallel argument demonstrates that $Z_c \beta_c \to -\infty$ is another inadmissible value of the maximum likelihood estimator.[1]

The key point to extract from this heuristic discussion is that changing a parameter in β_c alters the likelihood function in two ways: directly through its effect on rV and indirectly through its effect on the range of the unobservable ε_c. It is the second effect which substitutes for the identifying information achieved from the other statistics in the models presented in the preceding sections.

A more concrete example may prove helpful. Assume the sampling frame is such that $d = 1$. Let $f(x|\theta) = \theta e^{-\theta X}$. Assume c is a constant and let $\ln \lambda$ be

$$\ln \lambda = \mu + \varepsilon_\lambda$$

where ε_λ is a mean zero normal random variable with variance σ^2. The reservation wage is (see equation (1.12))

$$R = \frac{1}{\theta} (\ln \lambda - \ln c\theta) \geq 0 .$$

The probability that a person engages in search is

$$P(R \geq 0) = P(\frac{\varepsilon_\lambda}{\sigma} \geq \frac{\ln c\theta - \mu}{\sigma}) = \Phi(\frac{\mu - \ln c\theta}{\sigma}) .$$

where Φ is the cdf of a unit normal distribution.

---

[1] This argument is only a heuristic interpretation of first and second order conditions which the reader can supply. It is predicated on the assumption that the likelihood is not a monotonic function of η_c, and that η_c can be identified.

In this example, the restriction on the unobservable ε_λ (1.28) is

$$\{\varepsilon_\lambda \mid 0 \le \frac{1}{\theta} (\ln \lambda - \ln c\theta) \le x\}.$$

Substituting $\ln \lambda = \mu + \varepsilon_\lambda$ produces a more explicit restriction on the set of admissible $\varepsilon_\lambda, \{\varepsilon_\lambda \mid 0 \le \frac{1}{\theta} (\mu + \varepsilon_\lambda - \ln c\theta) \le x\}$. The density for x, t_u is (substituting for R in (1.27) assuming d = 1)

$$(1.30) \quad m^{**}(x, t_u) = \frac{\theta e^{-\theta X} e^{-c\theta t_u} e^{\mu}}{\Phi(\frac{\ln c\theta - \mu}{\sigma})} \int_{\frac{\ln c\theta - \mu}{\sigma}}^{\frac{\theta X + \ln c\theta - \mu}{\sigma}} e^{\varepsilon_\lambda / \sigma} \frac{1}{\sqrt{2\pi}} e^{-\frac{1}{2}(\frac{\varepsilon_\lambda}{\sigma})^2} d(\frac{\varepsilon_\lambda}{\sigma})$$

$$= \theta e^{-\theta X} e^{-c\theta t_u} e^{\mu + \sigma^2/2} \left[\frac{\Phi(\frac{\theta X - \mu + \ln c\theta - \sigma^2}{\sigma}) - \Phi(\frac{\ln c\theta - \mu - \sigma^2}{\sigma})}{\Phi(\frac{\ln c\theta - \mu}{\sigma})} \right]$$

The second line follows from standard results on the moment generating function of truncated normal random variables. Direct differentiation of the likelihood formed from (1.30) reveals that θ, c, μ and σ are identified.[1] Moreover standard asymptotic theory can be used to derive

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[1] An informal approach to identification notes that the hazard for exit to employment (h) is independent of λ. Thus h = cθ. Thus from the duration data, it is possible to estimate cθ. The density of accepted wages is (see (1.25))

$$\frac{1}{c} e^{-\theta x} e^{\mu + \sigma^2/2} \left[\frac{\Phi(\frac{\theta x - \mu + \ln c\theta - \sigma^2}{\sigma}) - \Phi(\frac{\ln c\theta - \mu - \sigma^2}{\sigma})}{\Phi(\frac{\ln c\theta - \mu}{\sigma})} \right].$$

Heuristically we can estimate θ from the linear term in x of a regression of the log empirical density of accepted wages. Departures from linearity in x identify θ/σ and hence σ. From the intercept it is possible to identify μ. Since cθ is known, θ is known and hence c is known. Note that there is additional information available from knowledge that a person is a labor force participant (which occurs with probability $\Phi(\frac{\ln c\theta - \mu}{\sigma})$).

Note further that little modification of the analysis in the text is required if we cannot distinguish individuals who are unemployed from those out of the labor force. Just note that the probability that a spell exceeds t is

$$P(T_u > t) = \Phi(\frac{\mu - \ln c\theta}{\sigma}) + e^{-(c\theta)t_u} \Phi(\frac{\ln c\theta - \mu}{\sigma})$$

so now there is duration dependence in the survivor function. (This is an example of the mover-stayer problem). From the survivor data it is clearly possible to estimate cθ and we can proceed with identification as is done above.

the asymptotic distribution theory of the maximum likelihood estimators.

A complete analysis of identification in a model with unobserved heterogeneity requires knowledge of the functional forms for $G(\varepsilon|\eta)$ and c, λ and θ. A nonparametric identification analysis of this model is impossible and for this reason the model is nonparametrically under-identified.[1]

Even when specific parametric functional forms are assumed, identification analysis is difficult for high dimensional G. Moreover, the analysis of Heckman and Singer (1981, 1982) demonstrates that parameter estimates obtained from nonlinear models of the sort described here are very sensitive to choices of functional forms for the distribution of unobservables, and so it is necessary to try a variety of functional forms for G to be sure that estimates and inferences are robust to changes in the assumed functional form of the distribution of unobservables. Because of computational cost, high dimensional G distributions are unlikely to be used in practice. Selecting which sources of hetero-geneity to model and which to ignore injects a further source of arbitrariness into the empirical procedure. For these reasons we claim that the greater simplicity in the asymptotic distribution theory for this model is offset by the arbitrariness inherent in "controlling for" unobserved heterogeneity.

We note that a procedure analogous to (but not identical to) the one presented in this section is appropriate if x is measured with error.

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[1] This conclusion is not special to a continuous time search model.

Thus if $x^* = x + \tau$ where τ is mean zero measurement error, and if $\varepsilon_c = \varepsilon_\lambda = \varepsilon_\theta = 0$, the range of τ is defined implicitly by

$$\{\tau \,|\, rV \leq x^* - \tau\}.$$

In place of (1.27) the density of x^*, t_u and d is

$$m^{**}(t_u, x^*, d) = \left\{ \int_{\{u \,|\, rV \leq x^* - \tau\}} \lambda f(x^* - \tau \,|\, \theta) \exp{-\lambda(1 - F(rV \,|\, \theta))t_u} \, dG(\tau) \right\}^d$$

$$x \left\{ \exp{-\lambda(1 - F(rV \,|\, \theta))t_u} \right\}^{1-d}$$

for $rV \geq 0$, where $G(\tau)$ is the cdf of τ. The likelihood is formed in the usual way. Assuming the model is identified, maximum likelihood estimators are consistent and asymptotically normally distributed.

1.5.C. Nonstationarity

There are many interesting and empirically relevant factors that produce a nonstationary model; finite lives for individuals (DeGroot, 1970), unemployment insurance available for a limited duration, etc. Nonstationarity raises two difficult problems. (A) The econometrician must be much more careful about the initial conditions of the process than has been required in the models analyzed up to this point (Flinn and Heckman, 1982). (B) Properly controlling for nonstationarity raises formidable computational problems (Heckman and Singer, 1982).

2. An Equilibrium Model of Sequential Search

2.0 Introduction

The one state model of sequential search analyzed in Section One is widely cited as the theoretical basis for empirical analysis of

unemployment durations. Its value as a guide to data has been questioned

because without modification it does not support a nondegenerate equili-

brium wage distribution (Diamond, 1971, Rothschild, 1973). This now

widely echoed objection has caused many applied economists to reject

search theory as an interesting source of hypotheses on unemployment

durations. Many would argue that developing the econometrics of an

economically uninteresting model puts the cart before the horse.

In this section we develop an equilibrium two state model of sequential

search. The model is closely related to recent work on matching equilibria

by Diamond and Maskin (1979). We demonstrate that the econometric frame-

work presented in Section One can be applied, with minor modification,

to the equilibrium model analyzed here.

The simplicity of the model proposed and estimated here may offend

the sensibilities of readers accustomed to regression analysis with

numerous "control variables." The simplicity of our model is charac-

teristic of the theory on which we draw. As discussed in Heckman and

Singer (1982) small departures from the stationary search model affect

the predictions from these models, the existence of optimal solutions

and the nature of the appropriate econometric model. For these reasons

we are reluctant to "throw in" numerous control variables in performing

our empirical analysis, especially variables that control for nonstationarity.

2.1 An Equilibrium Sequential Search Model

Labor market equilibrium is interpreted as the outcome of a steady

state sorting and matching process. Pools of unattached risk neutral workers

and firms are in the market seeking to form partnerships to perform tasks. Before

a worker and firm meet they do not know the potential rate of productivity

of a match. Thus ex ante all firms look alike to all workers and all workers

look alike to all firms. Upon encounter the productivity rate is perfectly

revealed. The time required to complete a task is an exponential random vari-

able. The distribution of the completion time of a task is beyond the control

of either party. Each member of a potential partnership gets half of the

total productivity of the match if it is consummated. There is a distribution

of match productivity rates in the population known to both workers and firms.

Values of potential matches are distributed independently across workers and

firms and are distributed independently across potential matches for the same

workers and firms. The outcome of one match is of no value in predicting the

outcome of another.

The probability that a worker meets a firm in a small time interval Δt

is less than one and the probability of two or more such encounters is negligible.

The probability of encountering a potential partner is assumed to follow the

Poisson probability law. The Poisson parameter of encounters depends on the

number of firms searching in the market. For simplicity we assume equal

numbers of unattached firms and workers (L) and that the rate of arrivals

to a given worker or firm is the same linear function of L. The symmetry of

the position of workers and firms is one possible justification for the 50-50

splitting rule assumed here.

Each party to an encounter has two options: (a) to accept the offered

terms of the match or (b) to continue searching. The task production tech-

nology is characterized by extreme indivisibilities such that partners can-

not search while working. If the prospective partners continue search they

incur an instantaneous flow rate of costs of c.

Search is with recall. If two prospective partners decide to continue searching they can consummate their match at a later time. However it is known from the theory of search in stationary environments (Lippman and McCall, 1976a) that they never consummate their match if they ever reject it. The intuitive reason for this result is that since the environment is stationary the attractiveness of any forsaken option is the same tomorrow as it is today.

This model generates equilibrium sequential search which is supported by a nondegenerate equilibrium wage distribution. It shares many features in common with the discrete outcome model of Diamond and Maskin although our interpretation differs somewhat from theirs.[1]

Each potential match has two characteristics: a flow rate of output $2x$ and a rate of termination σ. Distribution $F(x)$ is assumed to be absolutely continuous with finite absolute first moments. The value of a job to a worker who receives flow rate x (by virtue of the sharing assumption) is defined as $V_e(x)$.

It is determined by the following calculation.

$$(2.1) \qquad V_e(x) = \frac{1}{1+r\Delta t}\{x\Delta t + (1-\sigma\Delta t)V_e(x) + \sigma\Delta t\ V_u\}.$$

(Terms of order $o(\Delta t)$ are ignored.) The first term is the (discounted) value of

---

[1]An alternative model not estimated here is one due to Telser. His model generates the functional form of the equilibrium wage offer distribution but there is no search in equilibrium.

the flow x over the interval Δt. The second term is the (discounted) value of keeping the job times the probability of keeping the job $(1 - \sigma\Delta t)$. The third term is the (discounted) value of becoming unemployed (V_u) times the probability of becoming unemployed. Collecting terms and passing to the limit we reach

(2.2)
$$V_e(x) = \frac{x + \sigma V_u}{r + \sigma} .$$

As a consequence of $F(x)$ having finite absolute first moments V_u is finite. $V_e(x)$ is increasing in x and has bounded expectation. The agent is indifferent between a match that yields an x^* such that $V_e(x^*) = V_u$ and unemployment. For any $x \geq x^*$ the agent earns a rent with value $V_e(x) - V_u$. x^* is the reservation wage and it is defined as that value of x^* such that

$$V_e(x^*) = V_u = \frac{x^* + \sigma V_u}{r + \sigma}$$

so

$$x^* = rV_u.$$

The rate of arrival of encounters is $\lambda = g(L)$ assumed to be differentiable. The more participants that are searching in the market (<u>i.e.</u>, the higher L) the more rapid is the rate of arrival of encounters. $g(0) = 0$. $g'(L) > 0$ for all $L \geq 0$.

The value of unemployment is

$$(2.3) \qquad V_u = -\frac{c\Delta t}{1+r\Delta t} + \frac{(1-\lambda\Delta t)}{1+r\Delta t} V_u + \frac{\lambda\Delta t}{1+r\Delta t} E \max[V_e(x), V_u] \ .$$

(Terms of $o(\Delta t)$ are ignored.) The first term on the right is the discounted direct cost of search. The second term is the discounted value of remaining unemployed times the probability that no potential match is encountered $(1 - \lambda\Delta t)$. The third term is the probability of encountering a potential match $(\lambda\Delta t)$ times the discounted expected value of the two options that confront the agent: to take the match (with value to him of $V_e(x)$) or to remain unemployed (with value V_u). The expectation is computed with respect to the distribution $F(x)$.

Since the model possesses the reservation wage property, passing to the limit we may write (2.3) for $V_u > 0$ as

$$(2.4) \quad rV_u + c = \lambda \int_{rV_u}^{\infty} (V_e(x) - V_u)dF(x) = \frac{\lambda}{r+\sigma} \int_{rV_u}^{\infty} (x - rV_u)dF(x).$$

To assure that $V_u > 0$ it is required that

$$(2.5) \qquad\qquad c < \frac{\lambda}{r+\sigma} \int_{0}^{\infty} xdF(x).^{(1)}$$

---

[1] The proof is immediate from (2.3).

Note that $\lambda = (g(L))$ must be sufficiently large to support search behavior.
Thus in small markets (<u>e.g.</u> rural areas) search may not be undertaken.

The rate of exit from unemployment is

$$(2.6) \qquad\qquad h(t_u) = \lambda(1 - F(rV_u))$$

while the rate of exit from employment is

$$(2.7) \qquad\qquad h(t_e) = \sigma .$$

In steady state equilibrium, the number of individuals exiting unemployment must equal the number entering unemployment. Thus letting P be the total market size and L the total stock of unemployed, steady state equilibrium requires that

$$\lambda(1 - F(rV_u))L = \cdot \sigma(P - L)$$

where P - L is the total stock of the employed. Thus

$$(2.8) \qquad\qquad g(L)(1 - F(rV_u))L + \sigma L = \sigma P.$$

Condition (2.8) imposes further constraints on the problem. In particular for given values of the parameters there may be no value of L that solves (2.8) or there may be several. The minimum size of the unemployment pool that is required to support an equilibrium with search is (from condition

(2.5) using $\lambda = g(L)$ and the monotonicity of $g(L)$,

$$\underline{L} = g^{-1}\left(\frac{(r+\sigma)c}{\mu_x}\right)$$

where $\mu_x = \int_0^\infty xdF(x)$. Thus the higher the cost of search, the rate of interest and the rate of match termination and the lower the mean of the productivity distribution, the higher the unemployment pool must be to support a search unemployment equilibrium. Determination of the uniqueness of the equilibrium hinges on the functional form of the match distribution. For example, if $F(x)$ is exponential there is at most one equilibrium and there is always one for a large enough population P.[1]

Assuming a unique equilibrium, the unemployment rate is

$$\mu = \frac{L^*}{P} \quad .$$

The higher the cost of search and the lower the interest rate, the lower the equilibrium rate of unemployment. The effect of an increase in σ is ambiguous. Positive translations of the match productivity distribution reduce the equilibrium unemployment rate.

Condition (2.8) may be used in several ways in performing empirical work. It provides a check on estimates of the model because the aggregate unemployment rate μ should equal

$$\mu = \frac{\sigma}{\sigma + \lambda(1 - F(rV_u))} \quad .$$

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[1] To prove this, differentiate the left-hand side of (2.8) with respect to L and notice that it is monotone increasing in L.

It may also be used to eliminate one parameter from the estimation procedure.

2.2. Econometrics of the Two State Model

The statistical structure of the two state model so closely resembles that of the one state model that a lengthy discussion is unnecessary. Here we only explicitly consider the case of a homogeneous population.

The density of accepted wages is

$$(2.9) \qquad f(x|x > rV_u) \;=\; \frac{f(x)}{1-F(rV_u)} \,, \qquad x \geq rV_u.$$

The density of duration time spent in unemployment (t_u) is (defining $d_u = 1$ if a spell is uncensored and 0 otherwise) is

$$(2.10) \qquad \{\lambda(1 - F(rV_u))\}^{d_u} \exp -\{\lambda(1 - F(rV_u))t_u\}$$

where t_u is the measured length of a spell. Thus the joint density of accepted wages and duration t_u is

$$(2.11) \qquad m(t_u,x,d) \;=\; \{\lambda f(x)\}^{d_u} \exp -\{\lambda(1 - F(rV_u))t_u\}.$$

The density of match duration t_e is (defining $d_e = 1$ if a spell is uncensored and zero otherwise)

$$(2.12) \qquad g(t_e) \;=\; (\sigma)^{d_e} \exp -\{\sigma t_e\}.$$

These equations together with equation (2.4), inequality (2.5) and the requirement that accepted wages exceed reservation wages

(2.13) $x \geq rV_u$

define the full econometric model.

As in the one state model, inequality (2.13) is essential in securing structural estimates of the c and λ functions. Satisfaction of inequality (2.5) is essential to make the model economically meaningful. As in the one state model, the minimum of accepted wages (or any fixed order statistic) is a consistent estimator of rV_u. A recoverability condition for $f(x)$ is essential. If met we can estimate $f(x)$. From the hazard rate for leaving unemployment, λ may be consistently estimated and from the hazard rate for leaving employment σ may be consistently estimated. Provided condition (1.10) is met for F, we may condition on $r\hat{V}_u$ in the concentrated likelihood to secure $\sqrt{N}$ asymptotically normally distributed and consistent estimators of the structural parameters.

As a consequence of the homogeneity assumption spells may be pooled in the log likelihood function $\mathcal{L}$. Thus we may define

$$\mathcal{L} = \Sigma[d_u(\ln \lambda\, f(x)) - \lambda(1 - F(rV_u))t_u + d_e(\ln \sigma) - \sigma t_e].$$

The concentrated likelihood can be written as

$$\tilde{\tilde{\mathcal{L}}} = \Sigma[d_u(\ln \lambda\, f(x)) - \lambda(1 - F(r\hat{V}))t_u + d_e \ln \sigma - \sigma t_e].$$

For the case of exponential matches

$$f(x) = \theta e^{-\theta x}$$

we may write

(2.14) $\quad \tilde{\tilde{\mathcal{L}}} = \Sigma [d_u (\ln \lambda + \ln \theta - \theta x) - \lambda e^{-\theta r \hat{V}_u} t_u + d_e \ln \sigma - \sigma t_e].$

The maximum likelihood estimators of λ, θ and σ are, respectively,

(2.15a) $\qquad \hat{\lambda} = \dfrac{(\Sigma d_u) e^{\theta r \hat{V}_u}}{\Sigma t_u}$

(2.15b) $\qquad \hat{\theta} = \dfrac{1}{\Sigma d_u (x - r\hat{V}_u)}$

(2.15c) $\qquad \hat{\sigma} = \dfrac{\Sigma d_e}{\Sigma t_e}$.

Since condition (1.10) is satisfied

$$\sqrt{N} \begin{pmatrix} \hat{\lambda} - \lambda \\ \hat{\theta} - \theta \\ \hat{\sigma} - \sigma \end{pmatrix}$$

is normally distributed with mean zero and a covariance matrix that can be estimated by minus the inverse of the matrix of second partials of the log likelihood. A consistent estimator of search cost c may be obtained by solving from (2.4), and its standard error can be derived from the delta method.

2.3 Estimates of the Two State Model

This section reports maximum likelihood estimates of the parameters of two specifications of the two state equilibrium model. The first specification assumes that (firm or worker) match values are exponentially distributed; the second assumes that they are normally distributed. Both sets of estimates are derived under the assumption of homogeneity although we attempt to control for heterogeneity by estimating the model for one demographic group: young (20-24) white male high school graduates not attending school, sampled from the National Longitudinal Surveys in 1971. A more complete description of these data is given below (Table 1). To make the model empirically operational we define the unemployment state more broadly than is usually done to include unemployment as conventionally defined plus nonparticipation in the market.

The parameter estimates for the two models are presented in Table 1. The estimated reservation wage is \$1.50 (stated as an hourly rate). The mean length of a job $(\frac{1}{\sigma})$ is 28 months. For both models viability condition (2.5) is satisfied.

Table 2 records some of the more interesting features of these estimates. The first two rows record estimates of the cost of search (c) secured from equation (2.4). These estimates are obviously quite sensitive to the choice of interest rate r and the assumed functional form for the distribution of match productivities. The exit rate from the nonemployed ("search") state h_u is 1.21 which implies a mean length of nonemployment of 8.3 months. Given σ and h_u the implied equilibrium nonemployment rate is 22.5% which compares closely with the actual nonemployment rate

Table 1

Estimates of the Two State Equilibrium Search Model[*]

(Standard errors in parentheses)

λ (rate of arrival of job offers)	rV_u (reservation wage) \$/hr	θ (parameter of exponential match distribution)	M (mean of normal match distribution)	σ^2 (variance of normal match distribution)	σ (rate of termination of jobs)
		Exponential Model			
.201 (.008)	1.5 —	.339 (.038)	—	—	.035 (.035)
		Normal Model			
.1318 (.004)	1.5 —	—	3.325 (.34)	1.709 (.16)	.035 (.035)

The mean of the accepted wage offer distribution is $\bar{x} = 3.45$ and the variance is 1.464.

[*]The data are taken from the National Longitudinal Survey of Young Men, the first wave of which was collected in 1966. White, not enrolled in full time schooling (in 1971), hourly workers (determined by their current employment status) were used. The final requirement was made to eliminate the need to compute hourly wage rates for workers not paid on an hourly basis. We use data on lengths of employment and non-employment spells occurring in 1971. We use data on accepted wages to estimate the parameters of the wage distribution. Information from 231 complete and incomplete unemployment spells and 2915 complete and incomplete nonemployment spells is used. The data are available from the authors on request.

Table 2

Implications of the Estimates

(Standard errors in parentheses)

		Exponential Match	Normal Match
c - Implied cost of search	r = .05	1.139 (.616)	.327 (.148)
	r = .10	2.692 (1.86)	1.4547 (.643)
Implied Exit Rate from "Unemployment", $h_u (= \lambda(1 - F(rV_u)))$		1.21	1.21
Implied Equilibrium "Unemployment Rate" $(\mu = \frac{L^*}{P}) = \frac{\sigma}{\sigma + h_u}$		.225	.225
Actual "Unemployment* Rate" (1971)		.245	.245
Probability of encountering no match in the next six months		.30	.45
Probability of encountering one match in the next six months		.36	.36
Probability of encountering two or more matches in the next six months**.		.34	.19
Probability that a potential match will be accepted $(= \int_{rV_u}^{\infty} dF(x))$		.60	.92

*This is the CPS nonemployment rate for the group taken from Employment and Training Report of the President, 1976.

**Computed from the Poisson law $P(j) = \dfrac{(\lambda t)^j e^{-\lambda t}}{j!}$

of 24.5%.

As discussed in Section One, estimates of the rate of job offer or match arrivals are quite sensitive to the assumed functional form of the offer distribution. This is dramatically illustrated in panels four and five of Table 2. If an exponential model is assumed the estimated mean length of time between offers ($\frac{1}{\lambda}$) is five months and the probability of receiving no offer in the next six months is only .3. The probability of accepting a match that is offered is .6. Thus the exponential model implies a relatively rapid rate of arrivals of offers and a relatively frequent rate of rejection of those offers.

If a normal model is assumed, the story changes. In this case the mean length of time between offers is 7.5 months and the probability of receiving no offer in the next six months is .45. However, the probability of accepting a match that is offered rises to .92. Thus in the normal model, job arrivals are a relatively rare event and most workers accept the first job offer they receive.

In this particular case, the choice of model is clear. The accepted wage data are not exponentially distributed and an eyeball test indicates that the implied truncated normal distribution fits the data better. Before taking much comfort from this point, it is important to recall the point made in Section One. In order to estimate λ it is necessary to assume that the match offer distribution is recoverable. This requires making an arbitrary parametric assumption about the functional form of the productivity match distribution and the choice of this functional form will critically affect estimates of certain parameters of the model. Although we

can check the plausibility of any assumed functional form (assuming recovera-
bility) by inspecting accepted wage distributions, the power of such a test
is low. The recoverability condition cannot be tested.

Appendix B presents a three state model of labor force dynamics. Two
new points are made there. (A) Nonanticipated shocks in nonmarket time are
introduced. (B) A structural economic interpretation of the competing risks
model widely used in social science is provided. Point A is particularly im-
portant because it provides a good economic reason, not provided in this section,
for matches between workers and firms to dissolve. A worker (or entrepreneur)
may terminate a match in the model of Appendix B because of an unanticipated
increase in the value of nonmarket time. More general models of this type
are presented·in Coleman and Heckman (1981).

Summary and Conclusions

This paper takes a first step toward developing rigorous structural econometric models for the empirical analysis of labor force dynamics. The analysis is presented in continuous time although most of the new points raised here apply with full force to discrete time models. Rigorous structural estimation requires the solution of new problems that have not been addressed in previous work. We identify those problems and offer some solutions. We have also stated certain unsolved problems in the belief that their clear statement will focus attention on the relevant issues that should be addressed in subsequent econometric research on structural models of labor force dynamics.

A key condition required in our analysis is a <u>recoverability con-</u> <u>dition</u> that is implicit in all econometric analyses of truncated data of which structural models for the analysis of labor force dynamics are a special case. This condition must be satisfied in order to recover an untruncated distribution from a truncated distribution with a known point of truncation. A major conclusion of our analysis is that a recoverability condition will only be satisfied if the untruncated distribution is assumed to belong to a parametric family. It is not satisfied for all parametric families. Recoverability is not a testable proposition.

The implications of this analysis are far-ranging. Economic theory is rarely so specific as to predict the functional forms of untruncated distributions.[1] Thus, at its foundation, structural estimation in all

truncated data models involves an intrinsically arbitrary decomposition of reduced form parameters into structural components. Both formally, and by way of empirical examples, we have demonstrated that estimates of structural parameters are very sensitive to arbitrary choices made about functional forms required to empirically implement structural models. Put more succinctly, consistent non-parametric estimation of the parameters of most structural duration (and truncated data) models is impossible. The arbitrariness inherent in structural estimation is essential.

Granting the satisfaction of a recoverability condition (as the entire literature on the econometrics of truncated data has done) we have also demonstrated that structural estimation in a general class of dynamic labor force models requires the utilization of inequality constraints on accepted wage offers. Unless these constraints are used, the structural parameters of the model are not identified. Previous analysts have not noted this essential feature of these models.

Incorporation of the identifying inequality constraints into an estimation procedure raises certain nonstandard statistical problems. Conventional regularity conditions are violated so that the standard theory of maximum likelihood estimation does not apply. We develop the appropriate statistical theory for certain cases likely to be of interest in applications but we have not developed the general case in this paper, although we indicate how this might be done.

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[1] A notable exception is the analysis of Telser on equilibrium price and wage distributions.

We also formulate a structural two state _equilibrium_ matching model
of unemployment and estimate a simple version of it. Previous empirical
research on labor force dynamics has been conducted within the framework
of partial equilibrium search models which are not internally consistent
because they imply degenerate equilibrium wage distributions. The model
developed in this paper produces a nondegenerate equilibrium wage offer
distribution.

Empirical results obtained from this model provide an economically
meaningful decomposition of the parameters of reduced form exit rates
from unemployment. However, we demonstrate that the estimated structural
parameters are very sensitive to arbitrary assumptions about functional
forms of estimating equations. We demonstrate that two different behavioral
models are broadly consistent with the same data.

Our initial enthusiasm for structural estimation has been tempered
somewhat by the analytical and computational problems reported in this
paper. The econometric analysis of structural duration models is still
in its infancy. We are confident that subsequent analysis will solve
some of the problems left unsolved here.

Nonetheless, because much analysis of structural models remains
to be done, because basic facts on labor force dynamics remain to be
collated and analyzed and because of the inherent arbitrariness of the
identifying assumptions used to secure structural estimates (and the
sensitivity of estimates of structural parameters to such assumptions),
we also feel that a reduced form approach to analyzing labor force models

may be a useful complement to the structural approach presented in this paper. A companion paper (Flinn and Heckman, 1982) develops a reduced form approach to the empirical analysis of labor force dynamics.

Appendix A

The Maximum Likelihood Estimator
In the Case of More General Distributions for   Z

A complete analysis for the case of a general distribution for   Z   is a task for the future. Here we analyze the exponential example with no censoring for a case in which λ and c are positive constants and $\theta(Z) = \exp(Z_\theta\beta_\theta)$. Analysis of this example serves as a prototype for the more general case.

The model is that of equations (1.19), (1.20) and (1.21) in the text with $\lambda = e^{\beta_\lambda}$ and $c = e^{\beta_c}$. The sampling frame is assumed to be sufficiently long that $d = 1$. The log likelihood is

$$\pounds = N \ln \lambda + \Sigma(Z_\theta\beta_\theta - \exp(Z_\theta\beta_\theta)x) - c\Sigma e^{Z_\theta\beta_\theta} t_u$$

with constraints for each observation

(A-1)
$$x \geq e^{-Z_\theta\beta_\theta} (\ln \frac{\lambda}{c} - Z_\theta\beta_\theta)$$

$$\lambda, c > 0.$$

A critical aspect of this problem is that $\pounds$ is monotonically increasing in λ and decreasing in c and hence monotonically increasing in λ/c. The constraints are thus always effective in securing determinate solutions for

λ and c. It is useful to rewrite the first constraint as

$$(A\text{-}2) \qquad xe^{Z_\theta \beta_\theta} + Z_\theta \beta_\theta \;\geq\; \ln \frac{\lambda}{c}$$

As a consequence of the fact that $\mathcal{L}$ is monotone increasing in λ/c (for fixed β), the maximum likelihood estimator of λ and c is derived by choosing λ/c so that

$$(A\text{-}3) \qquad \ln\left(\widehat{\frac{\lambda}{c}}\right) \;=\; \min\left\{ xe^{Z_\theta \beta_\theta} + Z_\theta \beta_\theta \right\}$$

where the right hand side term is the minimum sample value of the term inside the braces. Exponentiating both sides, and substituting for c in $\mathcal{L}$ we reach a concentrated likelihood

$$\tilde{\mathcal{L}} \;=\; N \ln \lambda + \Sigma(Z_\theta \beta_\theta - \exp(Z_\theta \beta_\theta)x) - \lambda \exp\left[-\min\left\{ xe^{Z_\theta \beta_\theta} + Z_\theta \beta_\theta \right\} \right] \Sigma e^{Z_\theta \beta_\theta} t_u .$$

Maximum likelihood estimators of λ and β_θ are achieved by maximizing this function. c can be solved from (1.16).

The estimation strategy in this model is thus analogous to that presented in Section (1.4) except now we require an order statistic of a nonlinear function of x and Z_θ to secure estimates.

Define $M = xe^{Z_\theta \beta_\theta} + Z_\theta \beta_\theta$. For Z_θ iid the density $f(\cdot)$ of $M = m$ can be shown

to be[1]

$$f(m) = \frac{\lambda}{c} e^{-m} \qquad m \geq \ln\left(\frac{\lambda}{c}\right)$$

so the density of min {M} is

$$f(\min\{m\}) = \left(\frac{\lambda}{c}\right)^N e^{-N[\min\{m\}]} \qquad \min\{m\} \geq \ln\left(\frac{\lambda}{c}\right).$$

Assuming bounded parameters and bounded Z, min{M} is strongly consistent for $\ln(\lambda/c)$ and we conjecture that weak consistency of the mle estimators for λ, c and β_θ is an almost immediate consequence (assuming the population covariance of Z_θ is of full rank) and that the estimators for λ and β_θ can be shown to be asymptotically normal (with norming factor $\sqrt{N}$).

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[1]For a given value of β_θ and a density for Z_θ, $Z_\theta\beta_\theta$ has a density $h(Z_\theta\beta_\theta)$. The density of x conditional on $Z_\theta\beta_\theta$ and x satisfying constraint (A-2) is

$$f(x|Z_\theta\beta_\theta) = \frac{\lambda}{c} e^{-e^{Z_\theta\beta_\theta}x} \qquad x \geq e^{-Z_\theta\beta_\theta}(\ln\frac{\lambda}{c} - Z_\theta\beta_\theta).$$

The joint density of x and $Z_\theta\beta_\theta$ is

$$g(x,Z_\theta\beta_\theta) = \frac{\lambda}{c} e^{-(e^{Z_\theta\beta_\theta}x)} h(Z_\theta\beta_\theta) \qquad x \geq e^{-Z_\theta\beta_\theta}(\ln\frac{\lambda}{c} - Z_\theta\beta_\theta).$$

Use the definition of m given in the text, and applying standard change of variable methods

$$f(m) = \frac{\lambda}{c} \int e^{-m} h(Z_\theta\beta_\theta) d(Z_\theta\beta_\theta)$$

$$= \frac{\lambda}{c} e^{-m} \qquad m \geq \ln(\lambda/c).$$

The fact that $f(m)$ does not depend on the parameters of the Z_θ distribution and on β_θ is an artifact of the exponential example.

The argument can be extended to permit λ and c to depend on exogenous variables. For specificity we write λ, c, θ as in (1.19). K_λ is the number of parameters in β_λ and K_c is the number of parameters in β_c.

Inequality (A-1) which must be satisfied for each observation may be written as

$$(A-4) \qquad xe^{Z_\theta \beta_\theta} + Z_\theta \beta_\theta \geq Z_\lambda \beta_\lambda - Z_c \beta_c \ .$$

For any set of K_c values on the left hand side there are associated Z_c and Z_λ vectors. We define the units of Z_c so that any submatrix of K_c vectors of Z_c is positive.

Array the N values of the left hand side of (A-4) into a $N \times 1$ vector S. Define $[Z_c]$ and $[Z_\lambda]$ as the data matrices for the associated N values of Z_c and Z_λ. The vector of inequalities (A-4) may be written as

$$(A-5) \qquad S \geq [Z_\lambda]\beta_\lambda - [Z_c]\beta_c.$$

For the special but plausible case in which $Z_c = Z_\lambda$, this vector inequality can be written as

$$(A-6) \qquad S \geq [Z_c](\beta_\lambda - \beta_c).$$

From the assumed positivity of Z_c, the likelihood can be increased by

sending each element in β_c to minus infinity and each element of β_λ to plus infinity. Constraint (A-6) defines a region which is the intersection of the hyperplanes defined by each inequality in the vector of inequalities (A-6). To find the boundary of the intersection region solve the following linear programming problem.

Define P a positive vector conformable with $\beta_\lambda - \beta_c$. Let $\phi = (\beta_\lambda - \beta_c)$. Then find ϕ that solves the programming problem

$$\text{Max} \qquad \phi'P$$

$$\text{Subject to}$$

$$S \geq [Z_c]\phi .$$

The values of ϕ expressed as a function of P trace out a ϕ frontier. The maximum likelihood estimator selects a point on this frontier.[1] There are as many edges on the frontier as elements in $\beta_\lambda - \beta_c$ (i.e., $K_c = K_\lambda$). For any given value of β_θ and for given values of Z_θ, Z_λ and Z_c, the simplex algorithm may be used to solve for the frontier.

In an iteration cycle, for fixed β_θ and β_λ, it is thus possible, in general, to solve out for β_c as a function of β_λ, Z and β_θ. The likelihood function is then maximized with respect to β_λ and β_θ and new values of the frontier are solved out, etc.

Estimation in the more general case (A-5) proceeds along similar lines replacing S in the preceding paragraph with $S - [Z_\lambda]\beta_\lambda$ and ϕ with $-\beta_c$. Establishing the statistical properties of these estimators is a task left for the future.

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[1] This is so because the function is maximized by choosing the largest possible value of ϕ given any selected set of ratios in the P vector.

Appendix B

A Multistate Model of Labor Force Dynamics[1]

This appendix presents a prototypical model of labor force dynamics. With the exception of pioneering work by Toikka (1976), there are few examples of multistate structural models of labor force dynamics. The multistate models estimated by Marston (1976) were not given a structural interpretation.

Agents have linear utility functions and they are assumed to live forever. There is stochastic variation in the (monetary) value of nonmarket time in addition to stochastic variation in the wage offers received by agents. Variation in nonmarket time can arise because of variation in the demand for home time caused by children, illness, and the like. Considering such sources of unanticipated stochastic fluctuation in the value of non-market time (not known to the agent) enables us to produce a tractable economic model of labor force participation and job turnover that is especially helpful in explaining the labor force movements of women. Variation in the value of nonmarket time provides one motivation, not provided in Section 2, for termination of matches between workers and firms.

We permit wage offers to arrive while individuals are employed. Wage growth occurs over the life cycle as individuals take repeated drawings from common wage distributions. Burdett's model of on the job search (1978) ignores nonmarket participation and so his theory produces a life cycle theory of the growth of wages with age. Our model produces a theory of the growth of wages with work experience. Thus an individual who withdraws from the work force because of a high value of household time will forfeit his wage growth. That wages grow with work experience and not, primarily, with age, is the key finding of Mincer (1974) so that our model is more in accord with the facts than Burdett's and is especially suited to explain the wage growth of women. By permitting employed workers to receive job offers we also produce a simple model of job turnover.

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[1] This material is based on Coleman and Heckman (1981).

Our model also departs from previous work by permitting individuals who are not in the labor force to receive wage offers. Our model thus predicts that it is possible to observe individuals who transit from being out of the labor force to the employed state who never report themselves as being unemployed, as in fact is observed in the data. The labor market state "unemployed" is <u>defined</u> as that state in which the rate of arrival of job offers is higher than in the other labor force states. Individuals may choose to become unemployed if the rate of job offer arrivals in the state is sufficiently high. The cost of being unemployed is a direct money cost as well as the value of household time foregone. In order to make the unemployed state an economically viable option, the rate of arrival of job offers while unemployed must exceed the rate in the out of the labor force state.[1]

There are many other ways to model unemployment which we do not pursue here. Unemployment may simply be a nonmarket state in which individuals collect unemployment payments and consume nonmarket time. Given the fixed duration of most unemployment benefit programs, such a model would be inherently nonstationary although analytically tractable (i.e., it delivers qualitative results).

Our model is similar to one developed by Toikka. Both models consider search in an environment in which the value of household time changes randomly. Our model is more general in that (a) wage offers and changes in the value of nonmarket time are not constrained to arrive one per period as in his discrete time model and (b) we do not assume the arbitrary sequential ordering of decisions that he imposes in his model. The rate of time preference is ρ.

The distribution of wage offers $F(x)$ is assumed to be absolutely continuous with finite absolute moments. Successive wage offers are statistically independent. The value of nonmarket time is a random variable with distribution function $G(n)$

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[1] This insight is the basis of a test of search theory. See below.

with finite absolute moments. Successive values of nonmarket time are statistically independent. In all states the arrivals of new values of n are governed by a Poisson process with parameter μ. The probability of receiving a new value of n in the interval Δt is $\mu \Delta t + o(\Delta t)$.

In the employed state, wage offers arrive by a Poisson process with parameter λ_e. In the nonmarket labor state, wage offers arrive by a Poisson process with parameter λ_n. In the unemployed state wage offers arrive by a Poisson process with parameter λ_u, and to satisfy viability $\lambda_u > \lambda_n$ and $\lambda_u > \lambda_e$.

Employed workers may leave their current job for two reasons.[1] They may leave if a new value of household time n is drawn that is sufficiently high. They also may leave if they receive a wage offer elsewhere that is sufficiently high. To simplify the presentation we ignore any transaction costs in movement among these states, although the framework developed can readily be extended to accommodate such costs.

The value of a job that pays instantaneous wage x when a household opportunity n is available is V(x). It is determined by computing the expected value of all the outcomes that can occur to an individual who holds such a job.

There are three possibilities. First, in a small interval of time, no wage offer may be received and there may be no change in the value of nonmarket time. If it is optimal to hold a job at the beginning of the interval it is also optimal to hold it at the end. Second, the agent may receive a new nonmarket value of time n. (This could be due to birth of children or the like.) In this event he compares the value of staying on the job with the value of the nonmarket state defined here as S(n). The expected value of the maximum of these two options is computed at the beginning of the interval Δt and is a component of V(x). Third, the agent may receive a new market wage offer x' in time interval Δt. If this event occurs, he compares the value of the current job to the value of the offered job. Because of the Poisson assumption, the probability of receiving both a new wage and a new

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[1]Coleman and Heckman (1981) consider a more general model with exogenous terminations. In addition, they permit wage offers and nonmarket time offers to be correlated contemporaneously and over time.

nonmarket value in interval Δt is negligibly small.[1]

Thus $V(x)$ is defined as

$$(B-1) \quad V(x) = \frac{x\Delta t}{1+\rho\Delta t} + \frac{(1-(\lambda_e+\mu)\Delta t)}{1+\rho\Delta t} V(x) + \frac{(\mu\Delta t)}{1+\rho\Delta t} \underset{n'}{E} \max\{V(x), S(n')\}$$

$$+ \frac{(\lambda_e\Delta t)}{1+\rho\Delta t} \underset{x'}{E} \max\{V(x), V(x')\} + o(\Delta t)$$

The first term is the present value of wages x received over the next small interval of time Δt. The second term is the present value of the value of a job $(V(x))$ times the probability that no new wage offer is received $(1-\lambda_e\Delta t)$ times the probability that no new market offers arrive $(1-\mu\Delta t)$. Neglecting terms of order smaller than $o(\Delta t)$, $(1-(\lambda_e+\mu)\Delta t)$ is the probability of no new nonmarket offers, and no job termination. If this event occurs, the optimal policy is to continue working at wage x because no new information has arrived to change the agent's optimal decision, and because the optimal policy is stationary (because of the infinite life assumption).

The third term is the probability of receiving a new nonmarket draw $(\mu\Delta t)$ times the discounted expected value of the maximum of two options that exist if he receives such a draw: to continue to work at wage x $(V(x))$ or to switch to nonmarket activity with value $S(n)$. The expectation is computed with respect to the distribution of the value of nonmarket time $G(n)$.

The fourth term is the probability of receiving a new wage offer $(\lambda_e\Delta t)$ times the discounted expected value of the maximum of two options that exist if he receives a wage offer: to continue to work at wage x $(V(x))$ or to switch to a new job which pays wage x' with value $V(x')$. The expectation is computed with respect to the distribution of wage offers $F(x)$.

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[1] Note that if we permit exogenous job terminations, the value of nonmarket time is _not_ irrelevant in valuing a job. In the more general case considered in Coleman and Heckman, when an individual is terminated, he may be forced to accept an option that he rejected, including previously foresaken nonmarket opportunities.

S(n) is the value of household activity given nonmarket draw n. Its derivation is analogous to that given for V(x). Three things can happen to a person engaged in household activity at the beginning of interval Δt. (1) No new nonmarket or market draws arrive. This event occurs with probability $(1-(\lambda_n+\mu)\Delta t)$. In this case, the individual continues to stay out of the workforce. (2) A new nonmarket draw arrives. This event occurs with probability $\mu\Delta t$. If it does occur, the individual chooses the labor force option that gives the maximum of the new S(n) or the value of search Q. If he chooses to search, the individual is unemployed. (3) A market wage offer may arrive. This event occurs with probability $\lambda_n\Delta t$. If it does occur, the individual chooses the option with the highest value: he either continues on in the nonmarket state or takes the job offer. As before, the simultaneous arrival of a wage offer and fresh nonmarket draw is of negligible probability.

Defining Q as the value of search, we may write S(n)

$$(B-2) \quad S(n) = \frac{n\Delta t}{1+\rho\Delta t} + \frac{(1-(\lambda_n+\mu)\Delta t)}{1+\rho\Delta t} S(n) + \frac{(\mu\Delta t)}{1+\rho\Delta t} E_{n'} \max[S(n'),Q]$$
$$+ \frac{\lambda_n\Delta t}{1+\rho\Delta t} E_{x'} \max[V(x'),S(n)] + o(\Delta t) .$$

Q is derived by an analogous argument. A searching individual is assumed to consume no nonmarket time (an assumption that can easily be relaxed) and to incur instantaneous costs of search c. Thus we write

$$(B-3) \quad Q = \frac{-c\Delta t}{1+\rho\Delta t} + \frac{(1-(\lambda_u+\mu)\Delta t)}{1+\rho\Delta t} Q + \frac{\lambda_n\Delta t}{1+\rho\Delta t} E_{x'} \max[Q, V(x')]$$
$$+ \frac{\mu\Delta t}{1+\rho\Delta t} E_{n'} \max[Q, S(n')] + o(\Delta t) .$$

An unemployed individual may transit to employment or to the nonmarket participation state.

Formal properties of this model (and more general models) are established in Coleman and Heckman. A standard contraction mapping argument establishes the existence and uniqueness of an optimal policy under the stated conditions. The

model has the reservation wage property. (For a proof, see Coleman and Heckman.)

Define R_{en} as the reservation wage value of n that makes an employed individual who has just received a new nonmarket value of n indifferent between going to the nonmarket state and continuing to work at wage x. R_{ee} is the reservation value of x' that makes an employed individual indifferent between his current job with wage x and an offered job. In the absence of transactions costs, R_{ee} = x. R_{nu} is the reservation value of n that makes a nonmarket participant with a new value of n indifferent between staying on in the nonmarket state and switching to unemployment. It is implicitly defined by $S(R_{nu})$ = Q. R_{ne} is the reservation market wage that makes a nonparticipating individual with nonmarket value n indifferent between continuing in the nonmarket state and accepting a job. It is implicitly defined by $V(R_{ne})$ = S(n). R_{ue} is the reservation wage for an unemployed person and it is solved from $V(R_{ue})$ = Q. R_{un} is the reservation nonmarket draw that makes an unemployed individual indifferent between unemployment and nonmarket participation. It is implicitly defined by solving $S(R_{un})$ = Q.

The reservation wages are thus defined by the following equations:

(B-4a) $V(x) = S(R_{en}(x))$ (B-4b) $V(x) = V(R_{ee})$ so R_{ee} = x

(B-4c) $S(R_{nu}) = Q$ (B-4d) $V(R_{ne}(n)) = S(n)$

(B-4e) $V(R_{ue}) = Q$ (B-4f) $S(R_{un}) = Q$

Collecting terms and pressing to the limit ($\Delta t \to 0$), equations (B-1-B-3) become

(B-5) $$V(x) = \frac{x}{\rho} + \frac{\mu}{\rho} \int_{R_{en}}^{\infty} (S(n') - V(x))dG(n') + \frac{\lambda_e}{\rho} \int_{R_{ee}}^{\infty} (V(x') - V(x))dF(x)$$

(B-6) $$S(n) = \frac{n}{\rho+\mu} + \frac{\mu}{\rho+\mu} \int_{R_{nu}}^{\infty} (S(n') - Q)dG(n') + \frac{\lambda_n}{\rho+\mu} \int_{R_{ne}}^{\infty} (V(x') - S(n))dF(x') + \frac{Q}{\rho+\mu}$$

(B-7) $$Q = \frac{-c}{\rho} + \frac{\lambda_u}{\rho} \int_{R_{ue}}^{\infty} (V(x') - Q)dF(x') + \frac{\mu}{\rho} \int_{R_{un}}^{\infty} (S(n') - Q)dG(n')$$

This three equation system can be solved for the functionals V(x), S(n) and Q in terms of c, μ, λ_u, λ_e, λ_n and the parameters of dG(n) and dF(x). Using the reservation wage functions defined above, these three equations produce restrictions across the parameters of the transition matrix governing transitions

among the three states. (For more details, see Coleman and Heckman, 1981.)

The densities of duration times in each labor force state have a simple representation in terms of the reservation wages and arrival rates of offers. The econometric model produced by the theory is a competing risks model of the sort widely used in the duration analysis literature. (See Kalbfleisch and Prentice, 1980.) We establish the analogy by briefly reviewing that model using terminology from the biostatistics literature.

A patient can die from many causes that are assumed to operate independently. Suppose that there are two diseases, each of which is fatal. The time to death from disease one is t_1, if it is the only disease afflicting the patient, while the time to death from disease two is t_2, if disease two is the only one afflicting the patient. In the presence of both diseases, the time to death is $\min(t_1, t_2)$. t_1 and t_2 are clearly only hypothetical random variables each of which would characterize time to death if the other disease is not at work.

Suppose that each disease considered in isolation produces an exponential time to death. Thus

$$f(t_1) = h_1 e^{-h_1 t_1}$$

$$f(t_2) = h_2 e^{-h_2 t_2}$$

Direct calculation reveals that the time to death ($t = \min(t_1, t_2)$) has the density

$$f(t) = (h_1 + h_2) e^{-(h_1 + h_2)t} .$$

The probability that the patient dies from disease one is P_1 defined as

$$P_1 = \frac{h_1}{h_1 + h_2} = \int_0^\infty \int_{t_1}^\infty h_1 e^{-h_1 t_1} h_2 e^{-h_2 t_2} dt_2 dt_1 .$$

The competing risks model can be applied to the three state model of labor force dynamics. For example, an employed individual is subject to two risks: (a) getting a higher wage on another job and (b) getting a nonmarket draw that causes him to terminate his current job. Whichever risk occurs first causes him to exit his current job. Define $\tilde{t}_{ee}$ as the _hypothetical_ duration of employment in the

current job if the only possible exit is to another job. $\tilde{t}_{en}$ is the hypothetical

duration of employment if the only possible exit is to the nonmarket state. Each

random variable has an exponential distribution as a consequence of the time sta-

tionary Markovian process produced by the theory. The hazard rate for the density

of $\tilde{t}_{ee}$ is

$$(B-8) \qquad\qquad h_{ee} = \lambda_e(1 - F(x))$$

where x is the current wage in the employed state and the hazard for the density

of $\tilde{t}_{en}$ is

$$(B-9) \qquad\qquad h_{en} = \mu(1 - G(R_{en}(x))).^{[1]}$$

By the preceding argument, the density of the observed employment spell t_e

is the density of $\min(\tilde{t}_{ee}, \tilde{t}_{en})$

$$(B-10) \qquad f(t_e) = (h_{ee} + h_{en}) \exp -(h_{ee} + h_{en})t_e \quad.$$

Using methods exposited in Flinn and Heckman (1982), or Kalbfleisch and Prentice

(1980), it is possible to use duration data to consistently estimate h_{ee}

and h_{en} for each x. The probability that an individual

leaves his current job to take another job, P_{ee}, is

$$(B-11) \qquad\qquad P_{ee} = \frac{h_{ee}}{h_{ee} + h_{en}} \quad.$$

For exponential market and nonmarket wages with parameters θ_1 and θ_2 this model

is a logit in reservation wages and the current wage x:

$$P_{ee} = \frac{1}{1 + e^{a_e + \theta_1 x - \theta_2 R_{en}(x)}}$$

where $a_e = \ln(\mu/\lambda_e)$. Note that direct estimation of transition probabilities

enables us to estimate θ_1 (provided we solve for $R_{en}(x)$ from equations B-4 - B-7).

The density of accepted wage offers for individuals who quit one job with

wage x to get another with wage x' is

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[1] The analogy to competing risks model is somewhat strained because the reser-
vation wage rules for exit to one state would change if the other state were elim-
inated from this model. We ignore this point in constructing our analogy.

$$\frac{f(x')}{1 - F(x)} \qquad x' \geq x \ .$$

Given knowledge of x and x', and an assumed functional form for F, it is possible to estimate consistently the parameters of F as the number of observed e to e transitions becomes large. Consistent estimates of this density are __not__ possible without imposing a recoverability condition. Thus the model is nonparametrically underidentified but parametrically identified. Since it is possible to use duration data to consistently estimate h_{ee}, assuming recoverability is satisfied, λ_e can be consistently estimated (see B-8).

A parallel argument may be developed for transitions from other states. Thus the duration to time spent in an unemployment spell has density

(B-12) $$f(t_u) = (h_{ue} + h_{un}) \exp -(h_{ue} + h_{un})t_u$$

where

(B-13) $$h_{ue} = \lambda_u(1 - F(R_{ue}))$$

(B-14) $$h_{un} = \mu(1 - G(R_{un})) \ .$$

From duration by destination data it is possible to estimate consistently h_{ue} and h_{un} (See Flinn and Heckman, 1982).

The probabilities of exiting to e and n from u are

$$P_{ue} = \frac{h_{ue}}{h_{un} + h_{ue}}$$

$$P_{un} = 1 - P_{ue} \ .$$

For exponential market and nonmarket wages

$$P_{ue} = \frac{1}{1 + e^{a_u + \theta_1 R_{ue} - \theta_2 R_{un}}}$$

where $a_u = \ln(\mu/\lambda_n)$.

The density of accepted wage offers for individuals who exit from unemployment to employment is

$$\frac{f(x)}{1 - F(R_{ue})} \qquad x \geq R_{ue} \ .$$

From a sample of accepted wages for unemployed individuals it is possible to use the minimum accepted wage to estimate consistently R_{ue}. Hence it is possible to estimate consistently λ_u (from equation B-13), since it is possible to use the duration data to estimate consistently h_{ue}.

The density of time spent in a nonmarket spell is

(B-15) $$f(t_n) = (h_{ne} + h_{nu}) \exp -(h_{ne} + h_{nu})t_n$$

where

(B-16) $$h_{ne} = \lambda_n(1 - F(R_{ne}(n)))$$

(B-17) $$h_{nu} = \mu \, G(R_{nu}) \, .$$

As before, it is possible to use the duration by destination data to consistently estimate h_{ne} and h_{nu}. To simplify the exposition we assume that n is known.[1] The probabilities of exit to e and u from n are

$$P_{ne} = \frac{h_{ne}}{h_{ne} + h_{nu}}$$

$$P_{nu} = 1 - P_{ne} \, .$$

For exponential market and nonmarket wage

$$P_{ne} = \frac{1}{1 + e^{a_n + \theta_1 R_{ne} - \theta_2 R_{un}}}$$

where $a_n = \ln(\mu/\lambda_n)$.

From data on accepted wages in the n to e transitions it is possible to consistently estimate the reservation wage R_{ne} as the number of such transitions becomes large. Hence (from B-16) it is possible to estimate consistently λ_n, since it is possible to use the duration data to estimate consistently h_{ne}. Using (B-14) and (B-17) one can estimate μ (simply sum the two hazards). If n is observed, R_{nn} can be consistently estimated by the smallest n

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[1] This is an enormous simplification. Some data sets ask respondents questions which can be used to infer n. An analysis of the more general case in which n is unknown to the econometrician is presented in Coleman and Heckman (1981).

observed in the nonmarket state. Assuming recoverability, $G(n)$ can be consistently estimated.

Thus under the assumptions made, it is possible to consistently estimate λ_e, λ_n, λ_u, $F(x)$, μ, $G(n)$, R_{ue}, R_{en}, $R_{nu} = R_{un}$, R_{ne} and R_{ue}. The asymptotic distribution theory for these estimators is produced by an analysis similar to that given in the text, Part 1. For more detail see Coleman and Heckman (1981). In order to use the theory to secure structural estimates of the parameters of the model it is necessary to solve (B-4) – (B-7) iteratively to compute the reservation wage values needed to form the sample likelihood function. See Coleman and Heckman (1981).

The distinguishing feature of this model is that the theory imposes <u>cross transition</u> restrictions. These restrictions have not been noted or imposed in previous empirical work on labor force turnover. (See, <u>e.g.</u> Tuma and Robbins, 1980.) These restrictions aid in model identification and provide tests of the theory. We have already noted that the model predicts wage growth as a function of experience. By parameterizing nonmarket distributions we are able to produce a rich class of turnover models which enable us to introduce economic analysis from household economics into turnover models. Children, nonmarket income, health status and the like determine the value of nonmarket time.

Tests of hypotheses $\lambda_u > \lambda_e$ and $\lambda_u > \lambda_n$ provide indirect evidence on the empirical validity of search models. If, for example, $\lambda_u < \lambda_n$, considerable doubt would be cast on the standard search model. This hypothesis can be tested assuming that a recoverability condition is satisfied. For further analysis of this model and more general models see Coleman and Heckman (1981).

Appendix C: The Kiefer-Neumann Procedure

This Appendix discusses the relationship between the analysis in Section 1 of the text and the Kiefer-Neumann analysis of search unemployment (1979, 1981). We demonstrate that the Kiefer-Neumann analysis is critically dependent on the assumption that agents receive one offer per period (however the period is defined). We also note that even under their assumptions, their estimator is less efficient than the one presented in the text because they overlook a critical piece of information which we exploit. We further demonstrate that their inefficient estimation approach does not generalize to a continuous time setting and so cannot be used as a substitute for the analysis of the more general model given in the text.

The Kiefer and Neumann approach is a direct application of statistical results developed in the sample selection bias literature (see Heckman, 1976b and 1979 and Heckman and MaCurdy, 1981) and in the literature on female labor supply (see Smith, 1980).   F(x) is a log normal distribution so ln X is normally distributed with mean $z\beta$ and variance σ^2. Wage offers arrive one per "period". Following Lippman and McCall (1976) the reservation wage rV is defined as the solution to

(C-1) $$c + rV = \frac{1}{r} \int_{rV}^{\infty} (x - rV) dF(x)$$

for $rV \geq 0.$[1] We may solve for $R^* = rV$ (for r assumed known)

(C-2) $$R^* = R^*(c, z\beta, r).$$

Properties of R^* have already been established in the text (just fix $\lambda = 1$ in the analysis of section 1.1). Given their log normality assumption, it is convenient to work with

(C-3) $$R = \ln R^* = R(c, z\beta, r).$$

Conditional on z, the probability that an unemployment spell terminates at period j is (see section 1.2)

(C-4) $$P(j) = (F(R^*))^{j-1} (1 - F(R^*)) .$$

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[1] Kiefer and Neumann ignore this restriction in deriving their estimates.

Invoking log normality for X

$$(C-5) \qquad P(j) = [\Phi(\frac{R(c,z\beta,r)-z\beta}{\sigma})]^{j-1} \Phi(\frac{z\beta-R(c,z\beta,r)}{\sigma})$$

where Φ is the unit normal cdf. The density of accepted wages is

$$(C-6) \qquad f(x|X > R) = \frac{f(x)}{1-F(R)} .$$

For the log normal case,

$$(C-7) \qquad f(\ln x|\ln X > R) = \frac{(2\pi\sigma^2)^{-1/2}\exp-\frac{1}{2}\frac{(\ln x-z\beta)^2}{\sigma^2}}{\Phi(\frac{z\beta-R(c,z\beta,r)}{\sigma})} .$$

Using standard sample selection bias formulae (e.g., Heckman, 1976)

$$(C-8) \qquad E(\ln x|\ln X > R) = z\beta + \sigma\lambda(\frac{z\beta-R(c,z\beta,r)}{\sigma})$$

where

$$(C-9) \qquad \lambda(n) = \frac{(2\pi)^{-1/2}\exp-\frac{1}{2}n^2}{\Phi(-n)} .$$

The joint density of date to termination and accepted wages is

$$(C-10) \qquad P(j)f(x|X > R) = [F(R^*)]^{j-1} f(x)$$

$$(C-11) \qquad x \geq R^* .$$

Exactly as in the analysis of sections 1.3-1.5, the likelihood function formed from the joint density is monotonic in c and constraint C-11 is always satisfied as an equality for at least one observation.

Kiefer and Neumann do not maximize the likelihood for their model. Instead, they use an indirect two stage approach patterned exactly after previous models estimated in the female labor supply literature. They first use data on unemployment duration in a likelihood formed from (C-5) to estimate $\frac{R(c,z\beta,r)-z\beta}{\sigma}$, as a reduced form index. (This stage corresponds to estimating an equation determining whether or not a woman works.) Using this estimated index, they then follow previous econometric work in female labor supply and estimate λ (see equations (C-9) and (C-10)). From a regression of accepted wages on z and estimated λ it is possible (under conditions set forth in Heckman (1979) to consistently estimate β and σ.

From the estimated β and σ it is possible to solve from the estimated index $\frac{R(c,z\beta,r)-z\beta}{\sigma}$ for each observation, to estimate

$$R(c,z\beta,r)$$

for each observation. Using a nonlinear procedure, it is possible to consistently estimate c using the restriction implied in (C-1). Kiefer and Neumann (1981) use an iterated variant of this procedure.

The estimates derived from this procedure are not efficient because they do not exploit all the information in the sample (i.e., they are not derived from the likelihood function).[1] Moreover, the two stage procedure is critically dependent on the assumption that agents receive one offer per "period." In that case, the per period probability of accepting a job (1-F(R)) is also the denominator of the conditional density of wage offers. (See (C-6).) From the duration probit, it is possible to estimate the selection index ($\frac{z\beta-R(c,z\beta,r)}{\sigma}$) and so it is possible to correct for truncation bias in the estimated accepted wage offer distribution. In the more general case in which the probability of receiving an offer is less than one, the per period probability of accepting a job is not the denominator of C-6. (For a continuous time example see equations (1.4) and (1.5) in the text; the point applies to either a continuous time or discrete time model.) Thus in the more general case, if the rate of arrival of job offers is not known, it is not possible to estimate the selectivity variable (λ in equation (C-8)) from the duration data alone; thus the two stage procedure outlined above breaks down. Structural estimation requires utilization of the inequality restrictions exploited in Section 1.

Another point not noted by Kiefer and Neumann is that under the assumption that agents receive one wage offer per period, it is always possible to recover

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[1] One offsetting advantage is that their estimators are less sensitive to measurement error because they do not use extreme value observations while the estimators in the text are based on extreme observations. The efficiency comparison made in the text is rather stark. $\sqrt{N}(\hat{c}-c)$ obtained from maximizing the likelihood has zero large sample variance!

the untruncated wage offer distribution (above the truncation point) from the truncated distribution precisely because the denominator of the truncated distribution is known (see the discussion in section 1.3, especially on pages 10-11 and footnote 1 on page 11). Thus, provided that the reservation wage is estimated in the manner we suggest in the text, the untruncated distribution of wage offers is always recoverable from the sample truncated distribution if agents receive one wage offer per period. Thus it is not necessary to impose a functional form for accepted wages onto the data. Under their assumptions all the structural parameters of the model are nonparametrically identified.

Adding unobserved heterogeneity to the model in the fashion of Heckman and Willis (1977) or Kiefer and Neumann (1981) does not alter our conclusions in this Appendix in any fundamental way. For the sake of brevity, we refrain from extending our analysis to include this case.

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